

FEAR

Education & Training Department

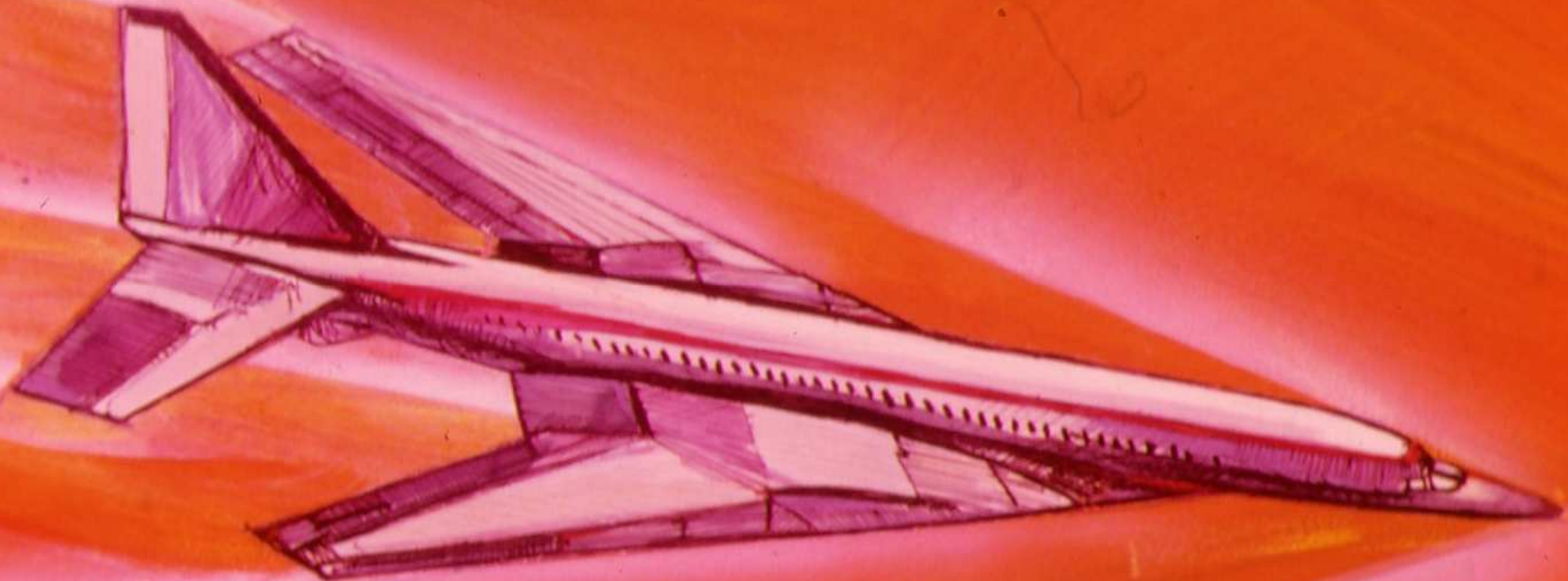
ELECTRONIC ASSOCIATES, INC.

West Long Branch, New Jersey

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Understanding the ANALOG/HYBRID Computer







THESE EXTRAORDINARY EVENTS

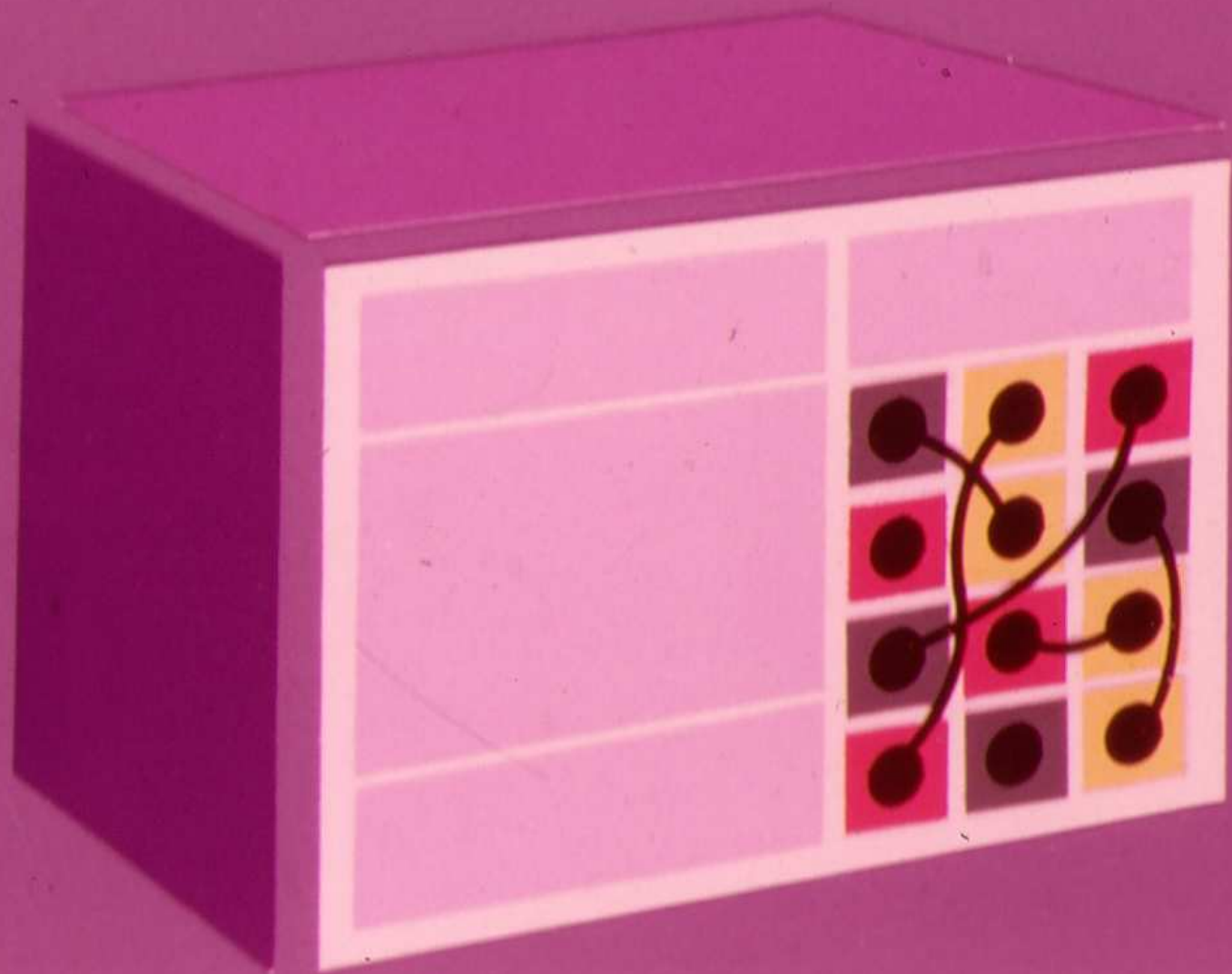
ARE BEING REHEARSED DAILY

UNDER ALL POSSIBLE

CIRCUMSTANCES....

..... ENGINEERING DESIGNS ARE
BEING MODIFIED AND PERFECTED
--- QUICKLY, ECONOMICALLY, AND
SAFELY, THROUGH THE USE OF....

The ANALOG/HYBRID Computer



1.

What is an Analog/Hybrid computer?

2.

How and where is it used?

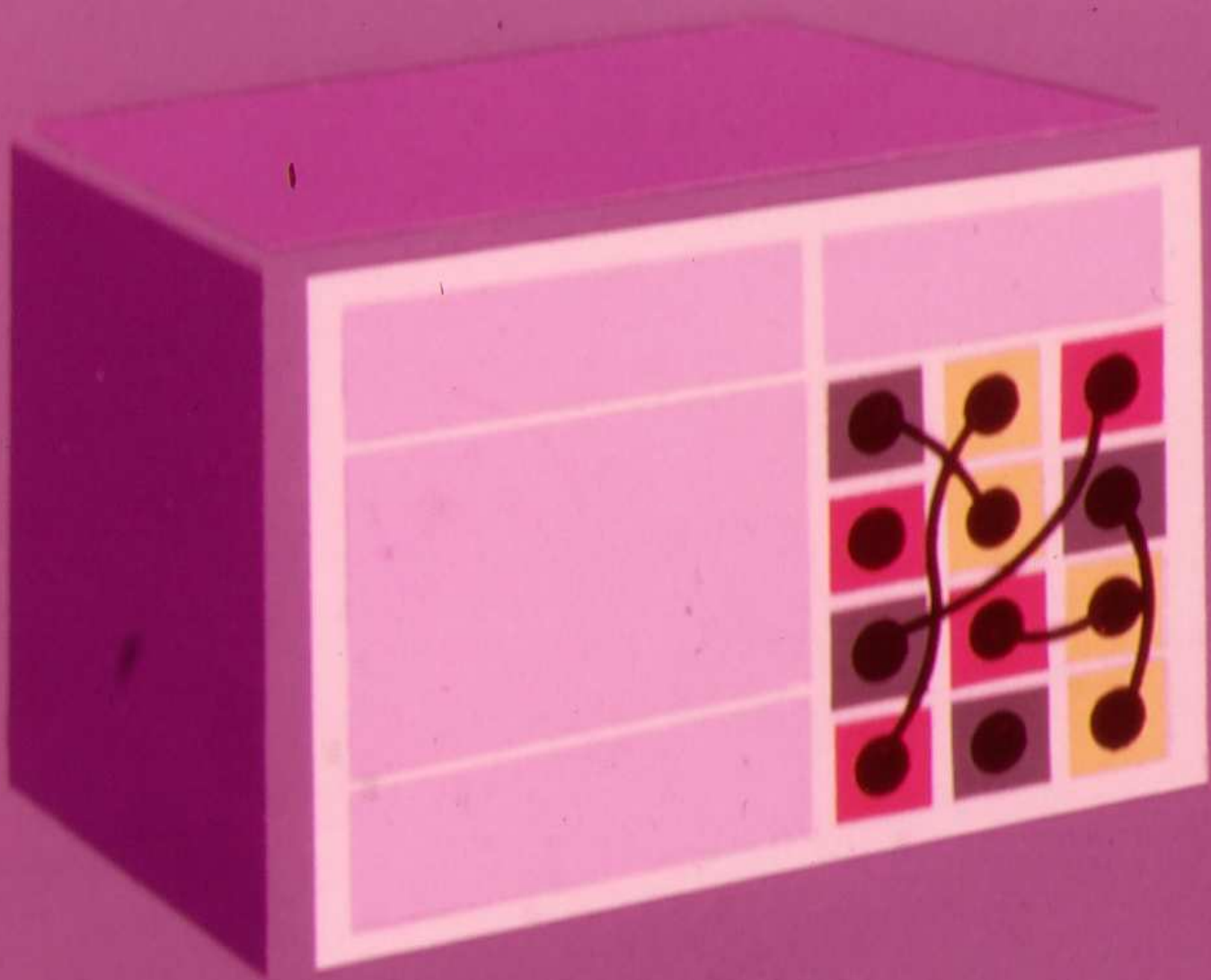
3.

How does it compare with other types of computers?

ANALOG COMPUTERS
SOLVE PROBLEMS BY



SIMULATION



$$e = \frac{1}{2} a \tau^2$$



$$S = \frac{1}{2} g t^2$$

+Reference

+1.0000 Units

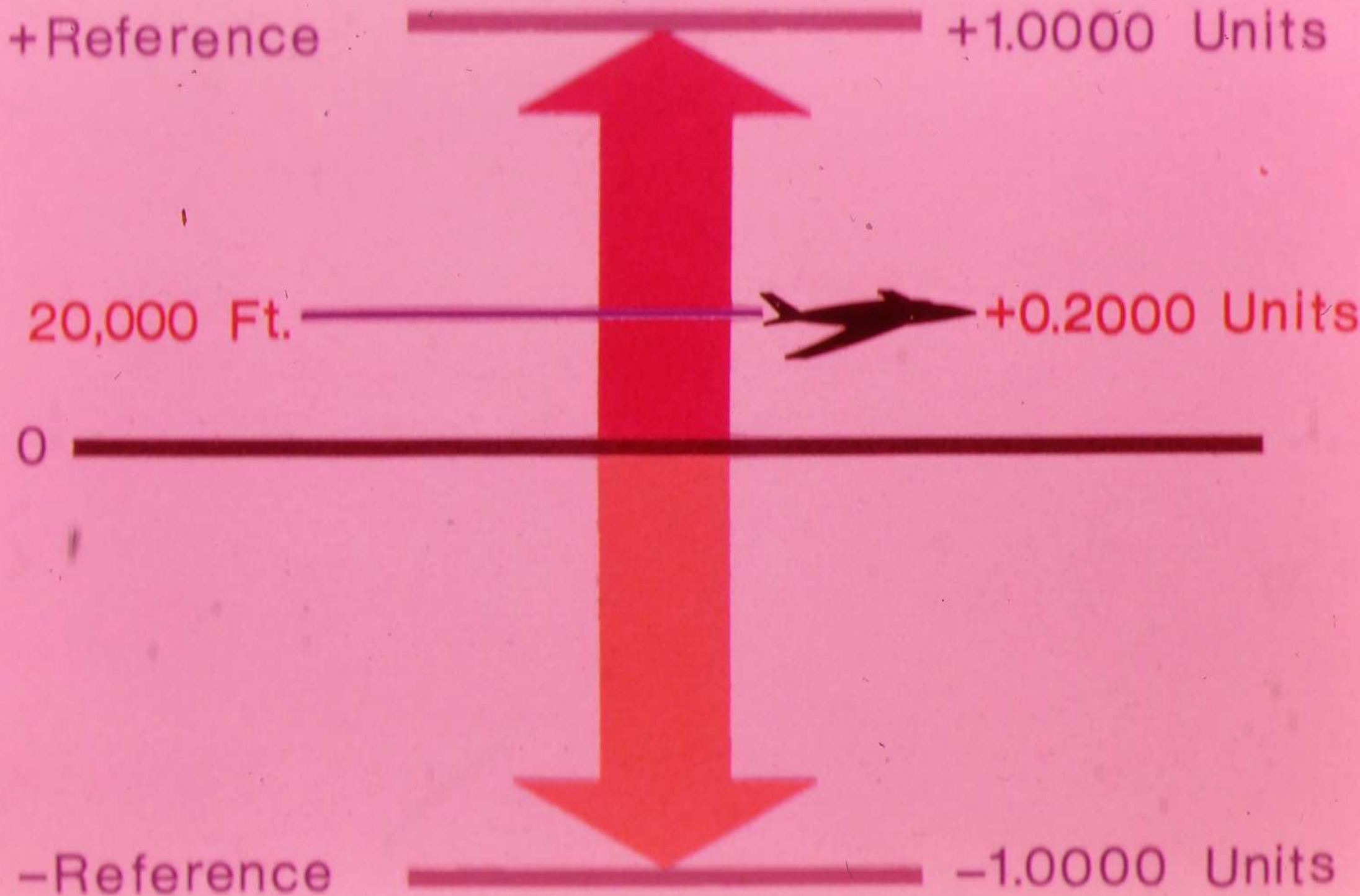
20,000 Ft.

+0.2000 Units

0

-Reference

-1.0000 Units

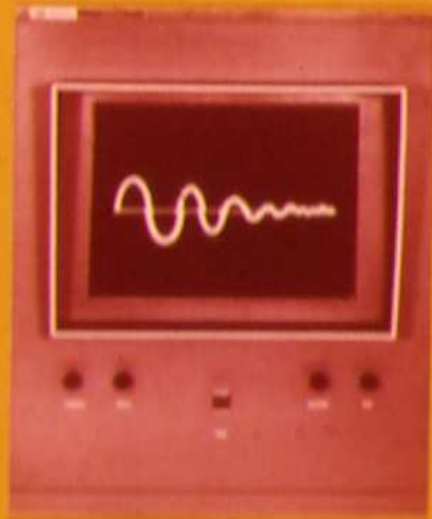


+0.8 0 3 5

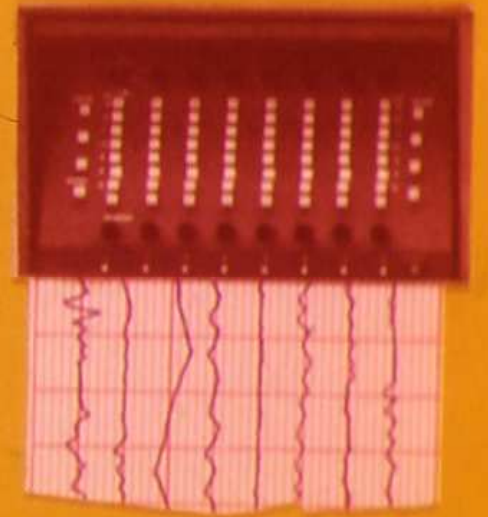
Digital Voltmeter



X-Y Plotter



Display Scope



Recorder

Control panel with two digital displays on the left, a central control knob, and a large grid of indicator lights on the right.

Panel featuring a large dark rectangular display at the top, a digital readout showing "0 5 2 4 8" below it, and a small analog gauge with two control knobs at the bottom.

Panel with two columns of four indicator lights each, and two rows of five control knobs each.

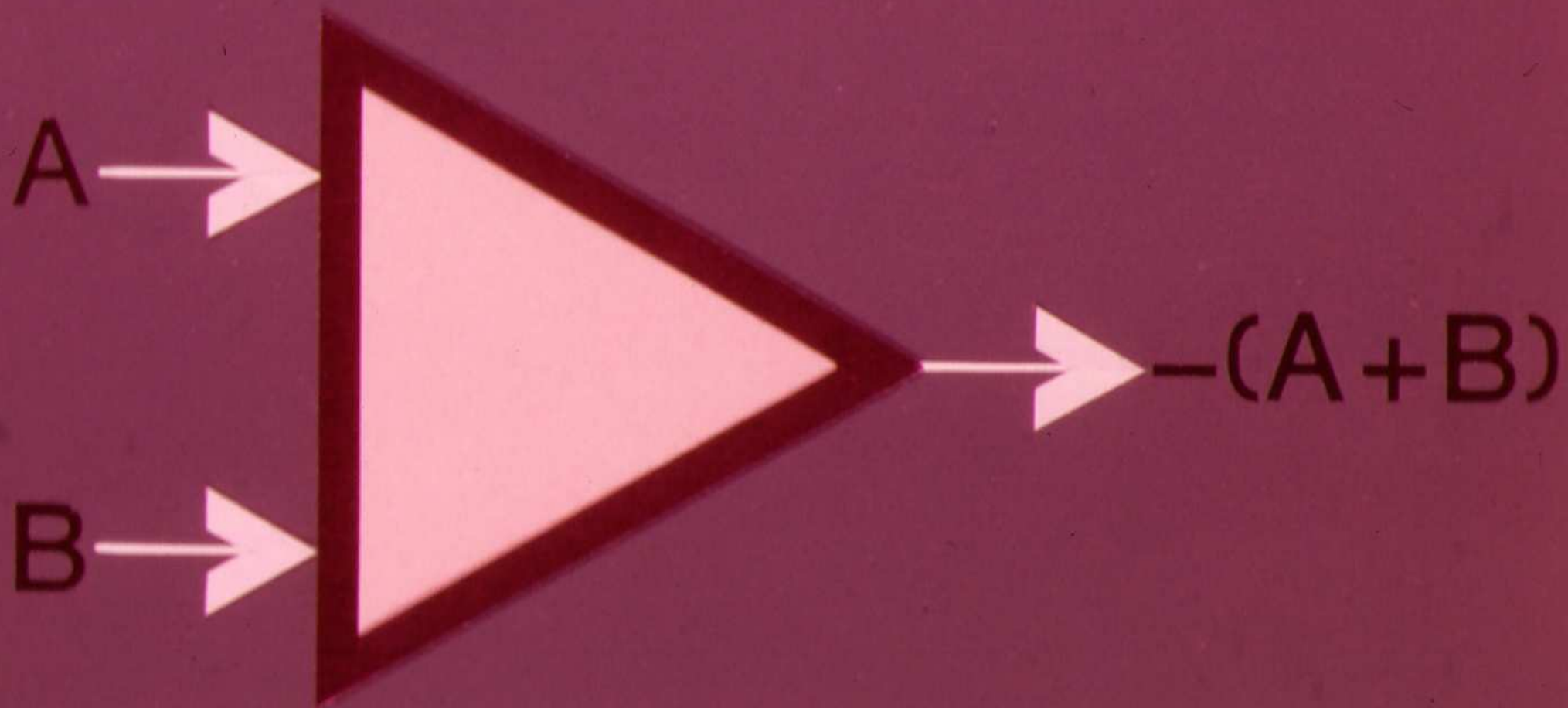
Panel with two columns of indicator lights, several control knobs, and a small analog gauge on the right side.

Large panel containing a grid of numerous small indicator lights and control elements, organized into four horizontal rows.

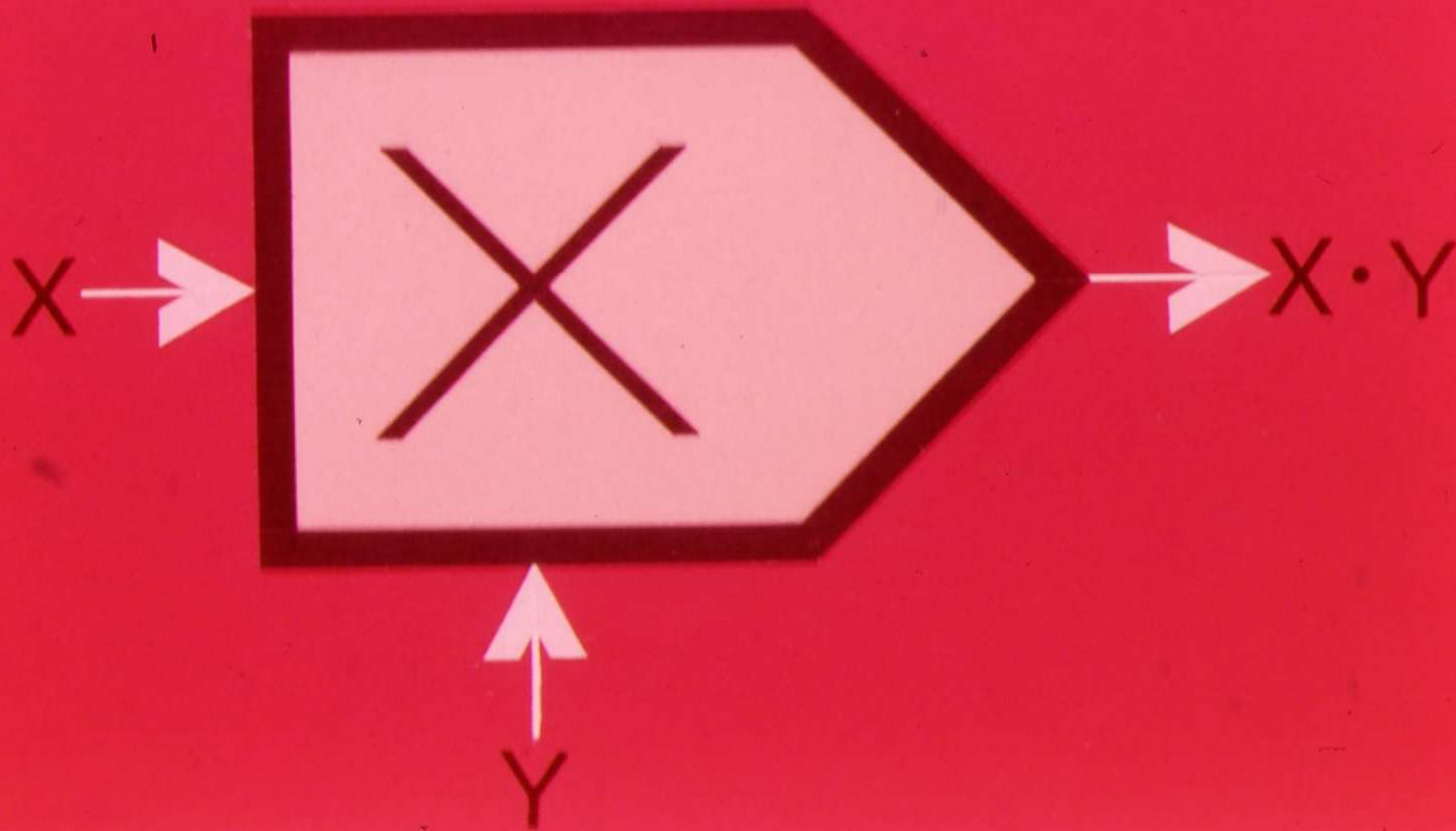
Panel with a label "EAI 000" and a dark rectangular area to its right.

- 1. Summers**
- 2. Multipliers**
- 3. Potentiometers**
- 4. Function Generators**
- 5. Integrators**

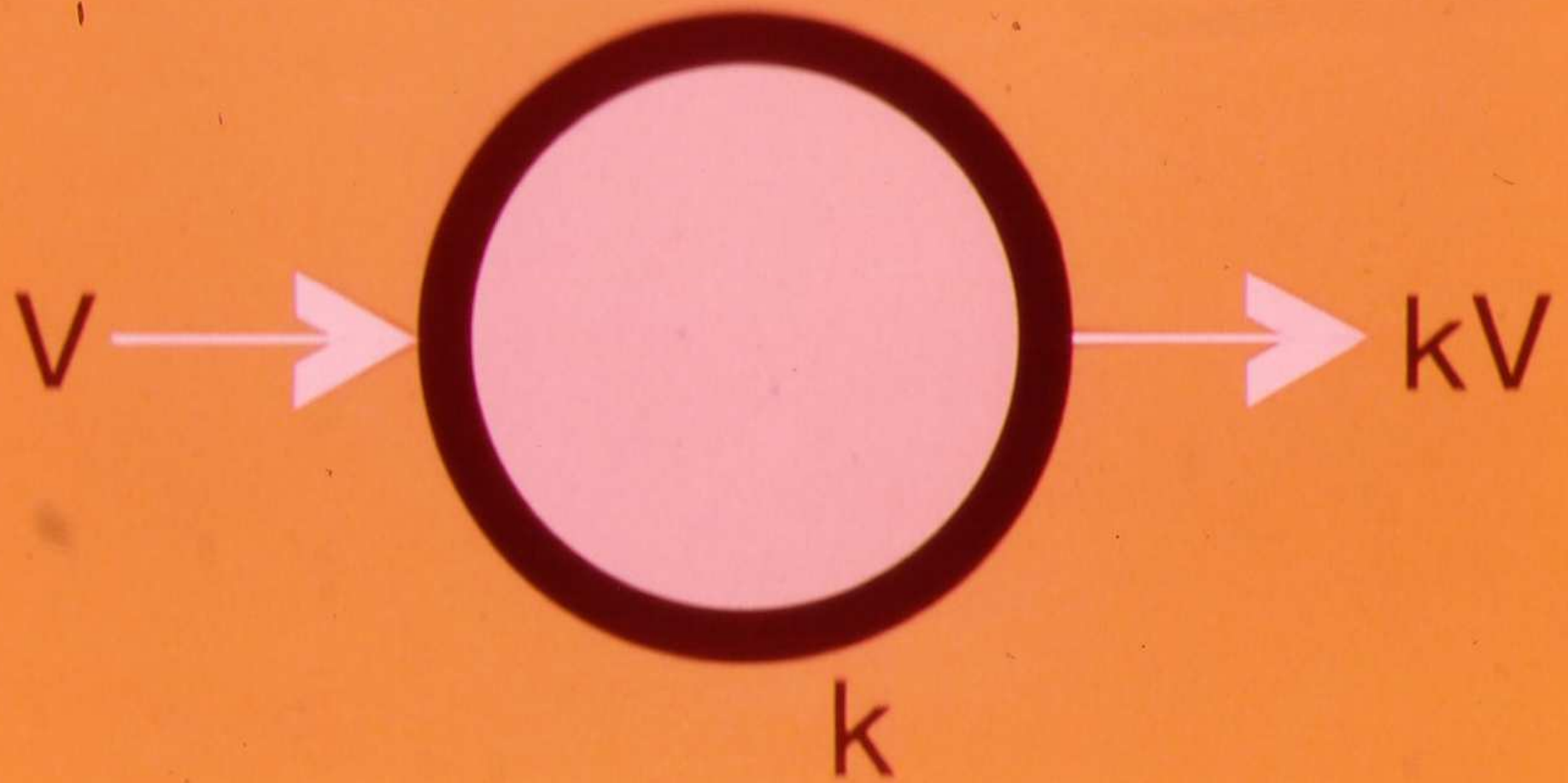
SUMMERS



MULTIPLIERS



POTENTIOMETERS



P04

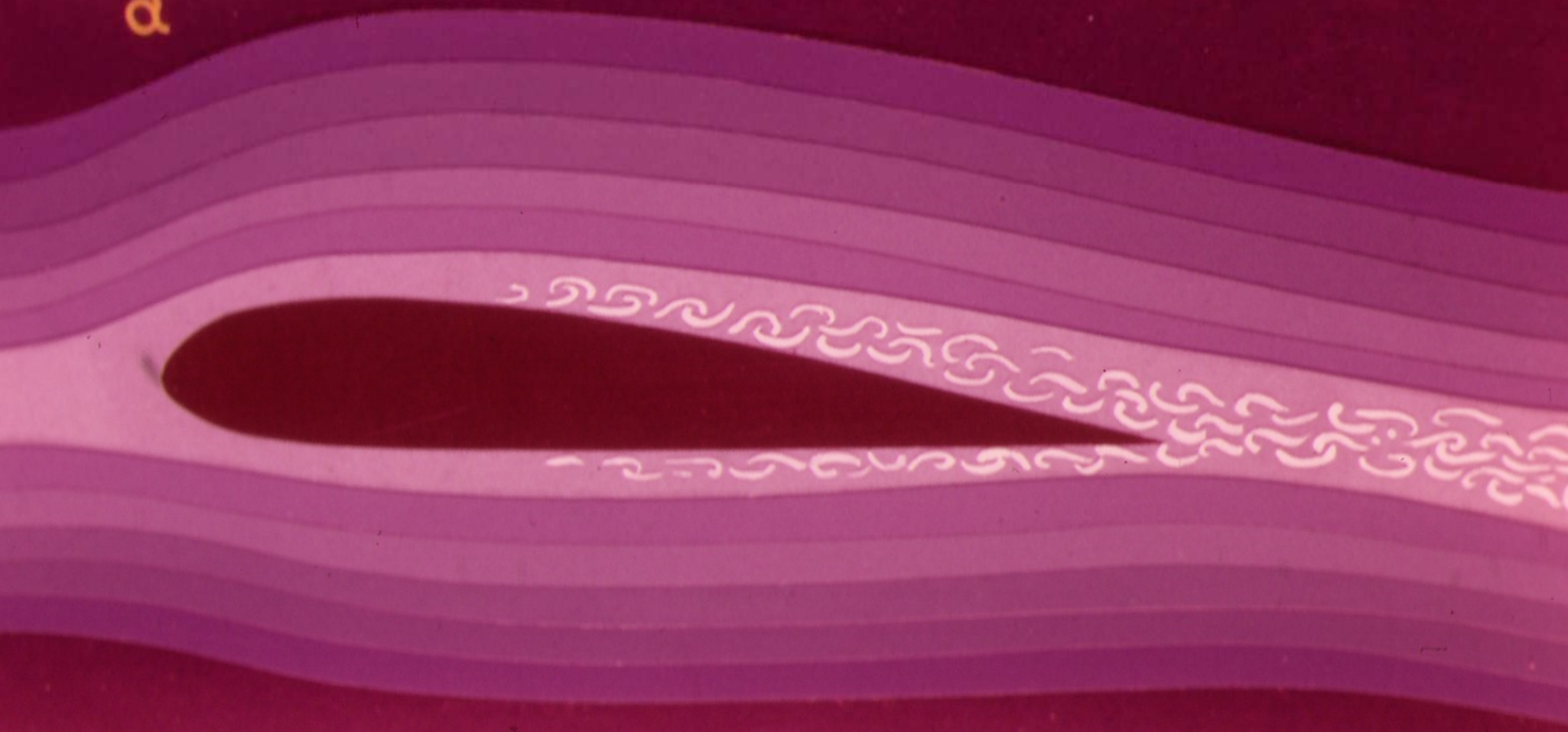


FUNCTION GENERATORS



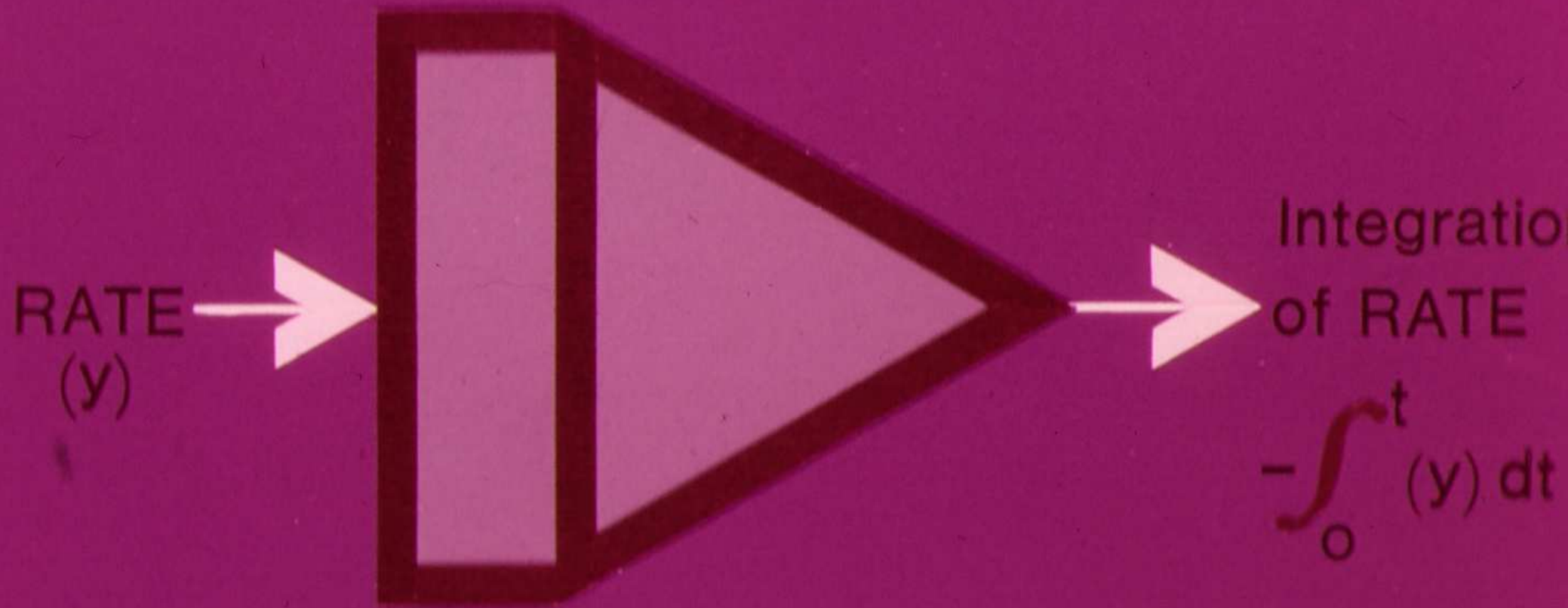


ANGLE
OF
ATTACK
 α





INTEGRATORS





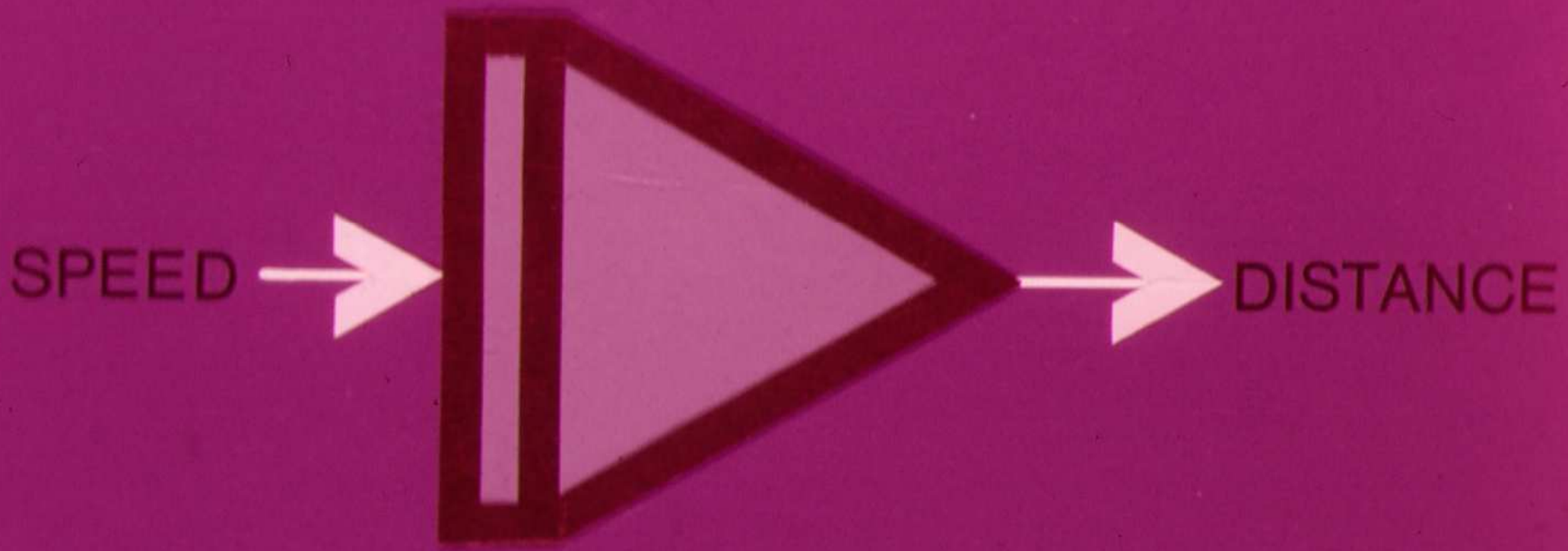
FLOW RATE



HEIGHT =

{ Integration
of Flow Rate
+ Initial Height

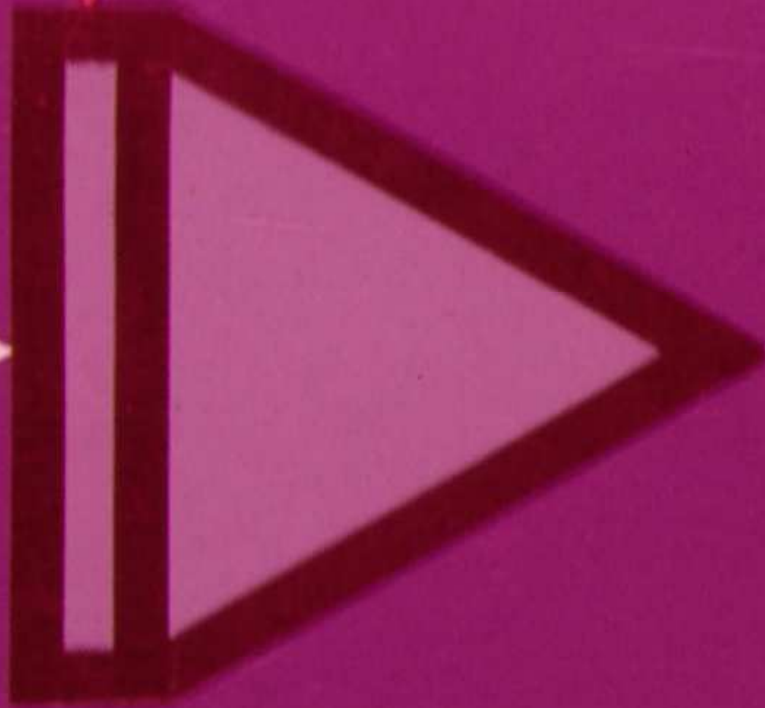
2 3 8 6 07



INITIAL
DISTANCE

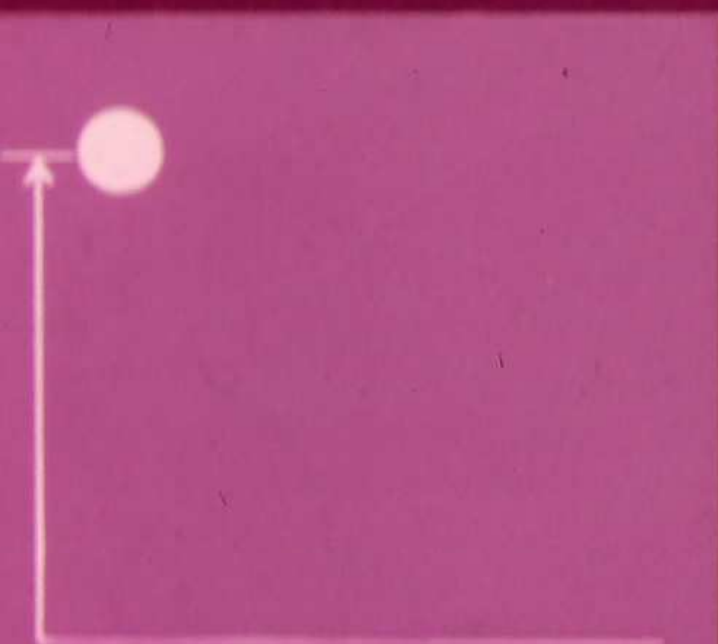


SPEED



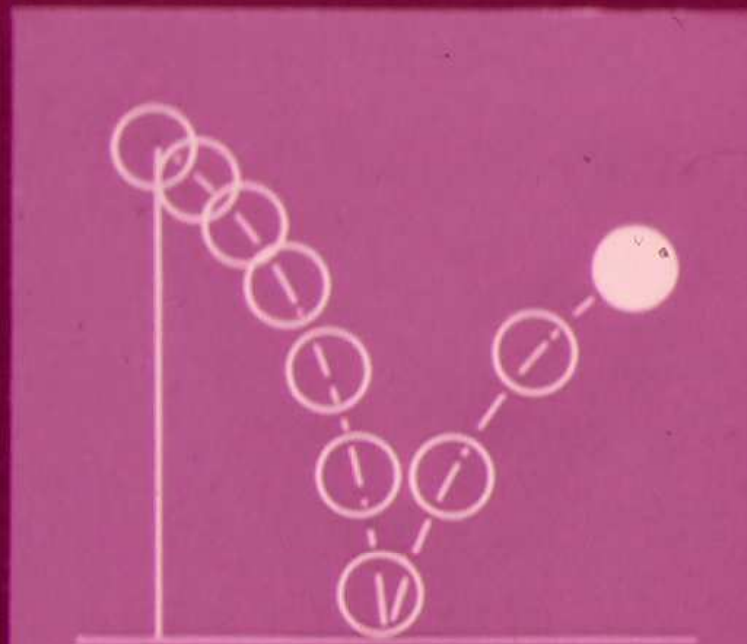
DISTANCE

COMPUTER MODES



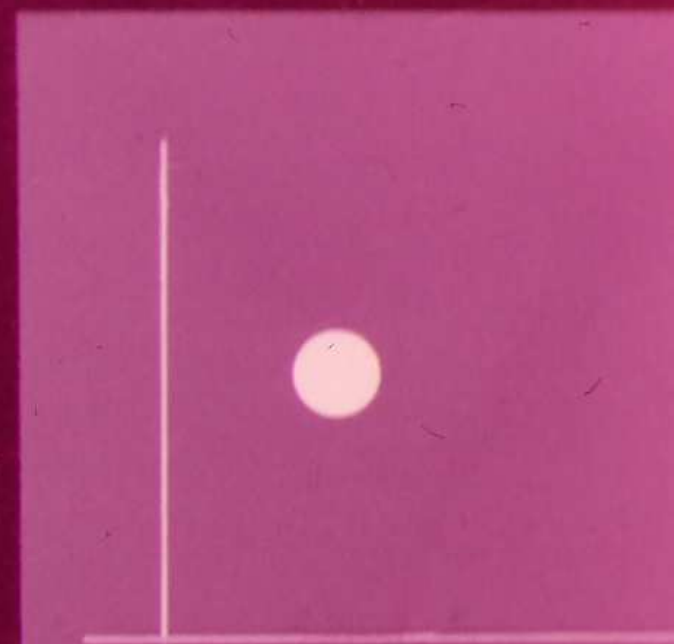
Initial
Condition

IC H OP



Operate

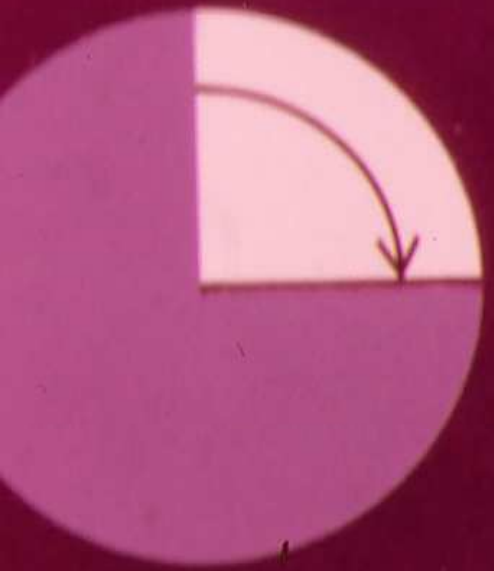
IC H OP



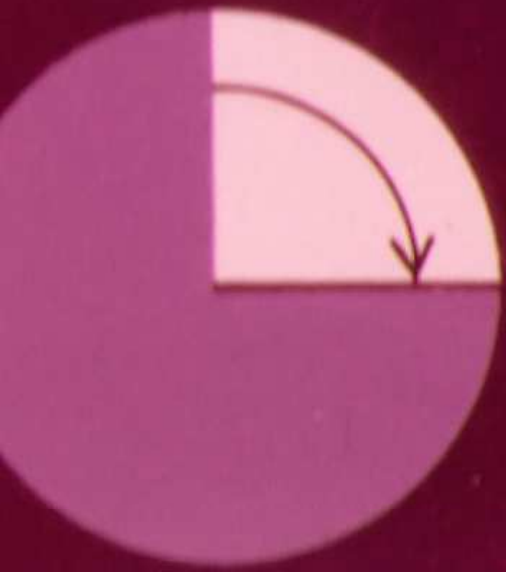
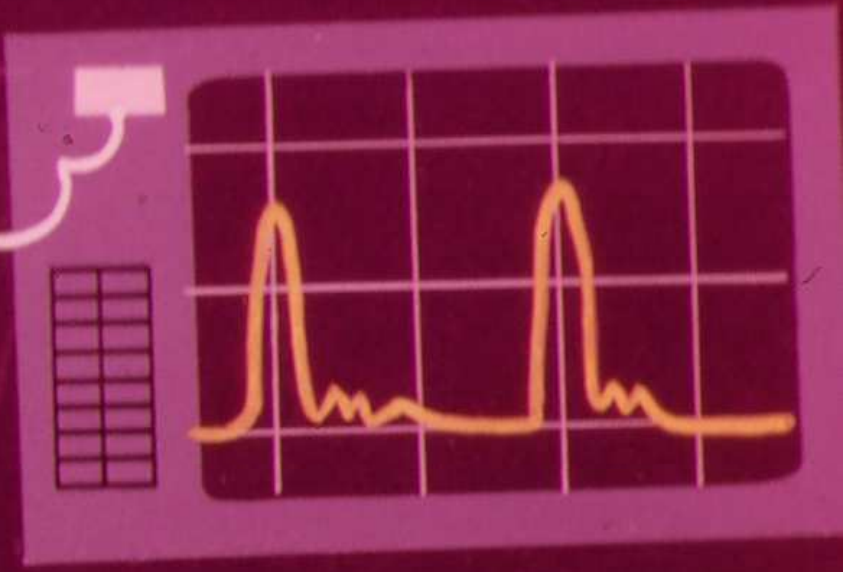
Hold

IC H OP

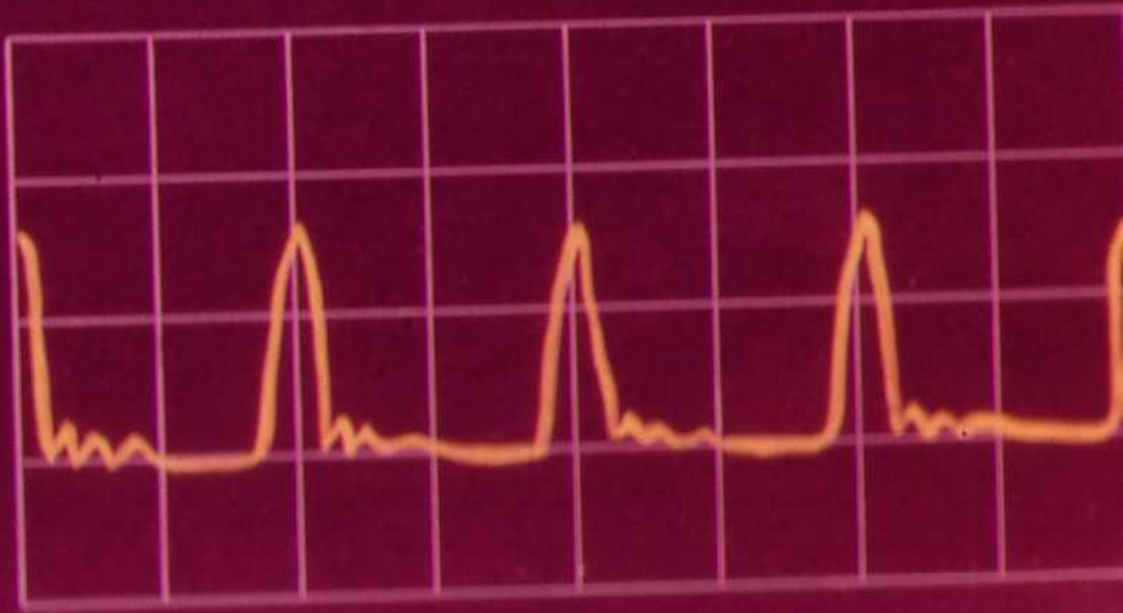
REAL TIME SIMULATION



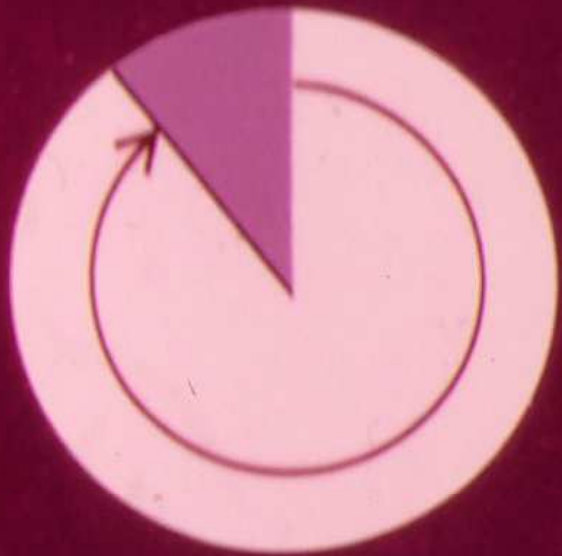
Physical System



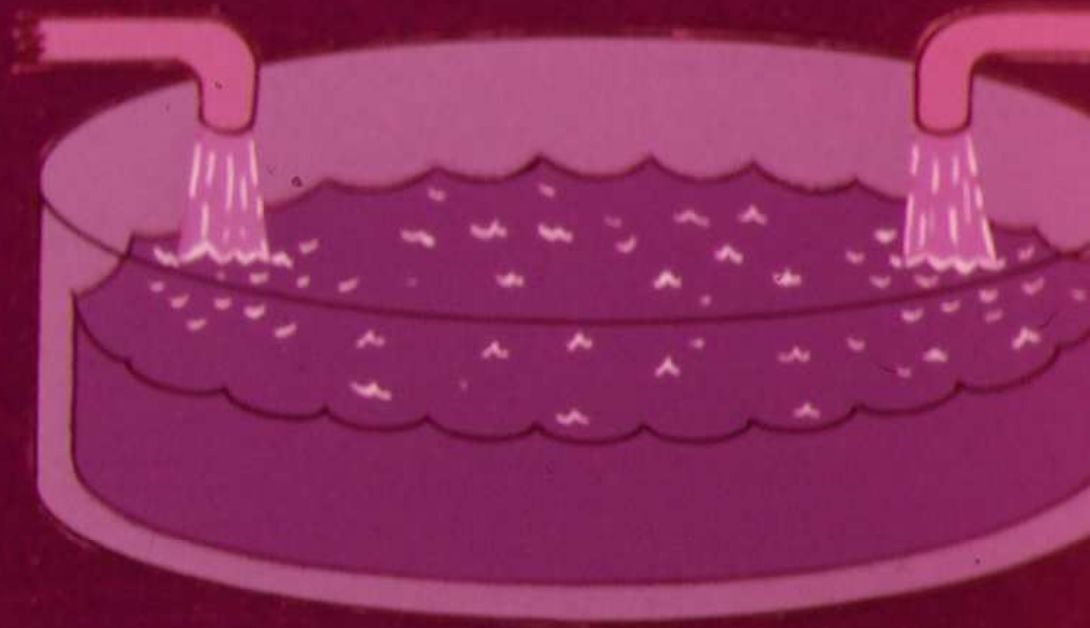
Computer Simulation



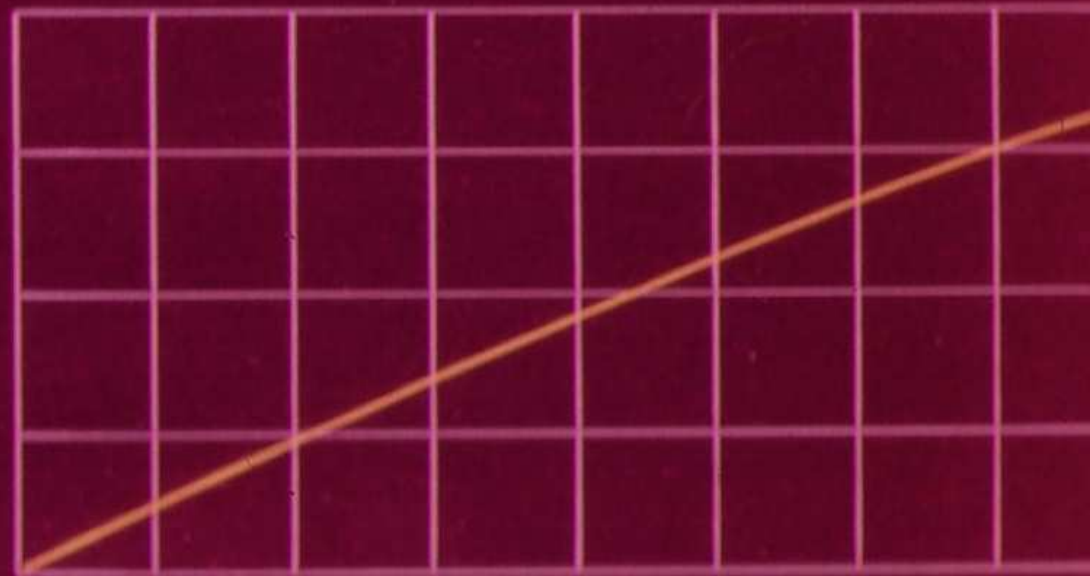
FAST TIME SIMULATION



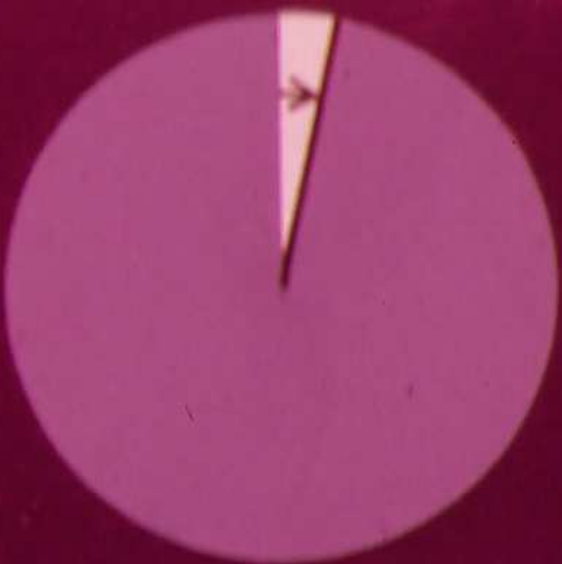
Physical System



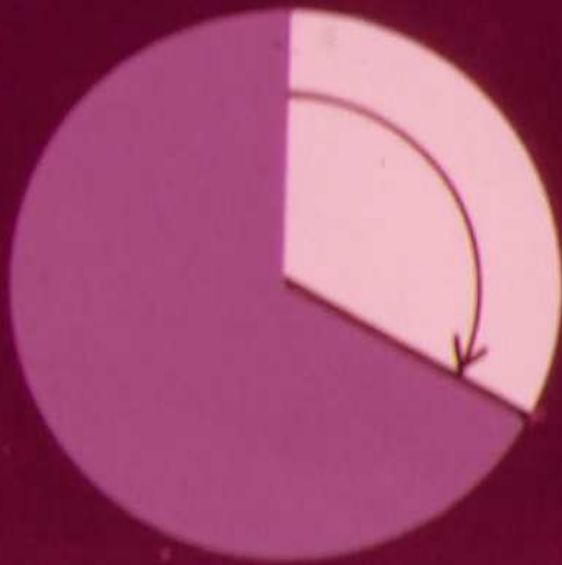
Computer Simulation



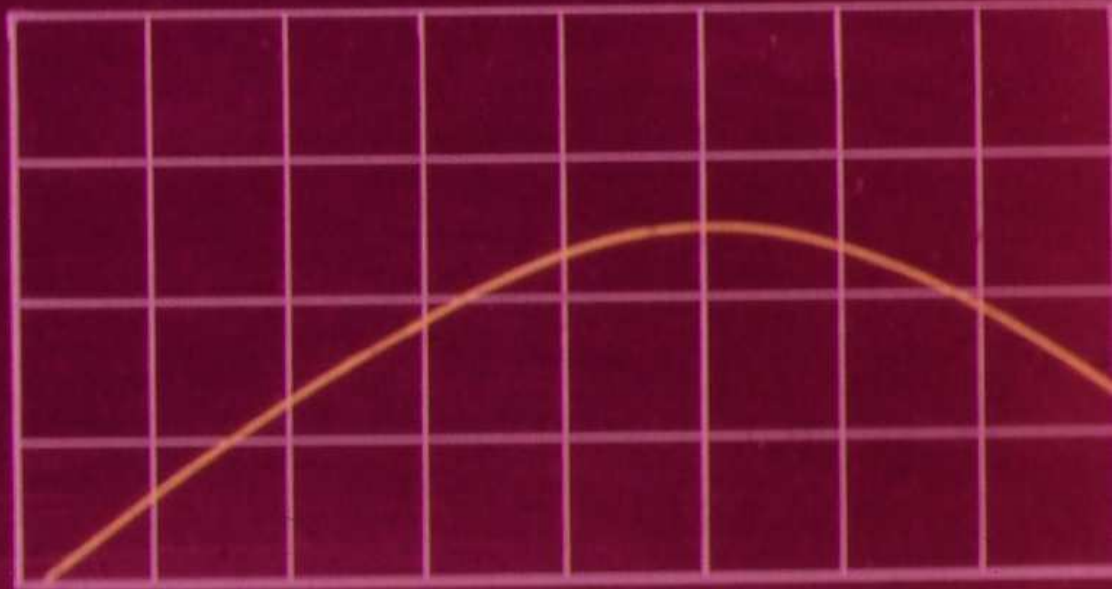
SLOW TIME SIMULATION

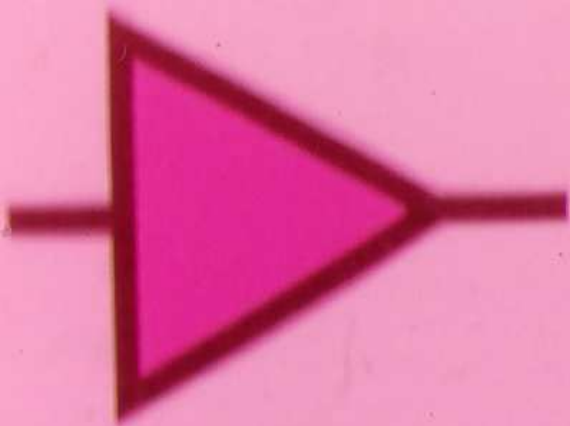


Physical System



Computer Simulation





Summers



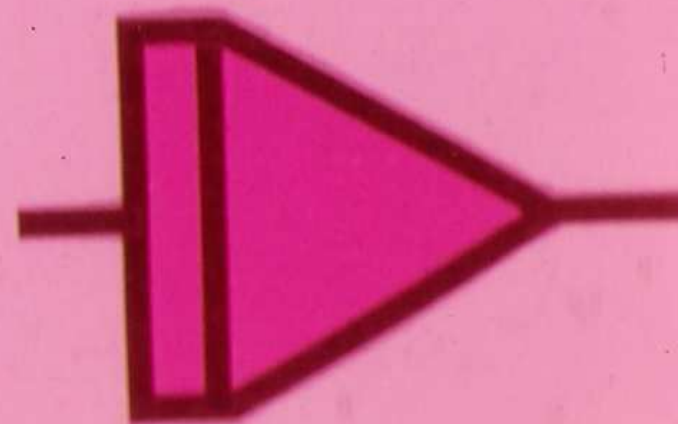
Potentiometers



Multipliers



Function Generators



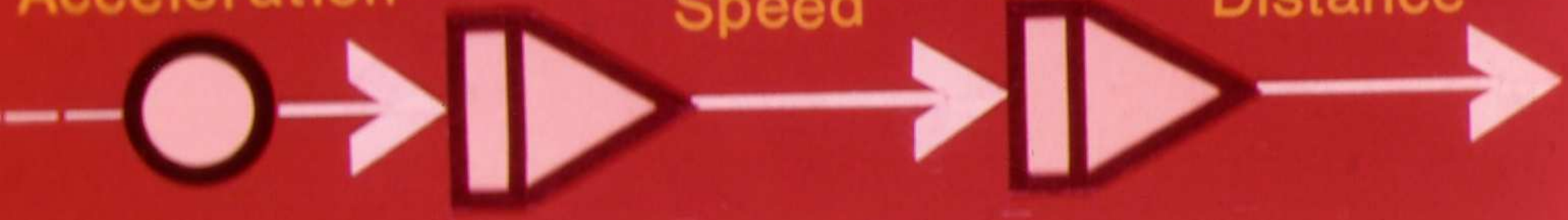
Integrators

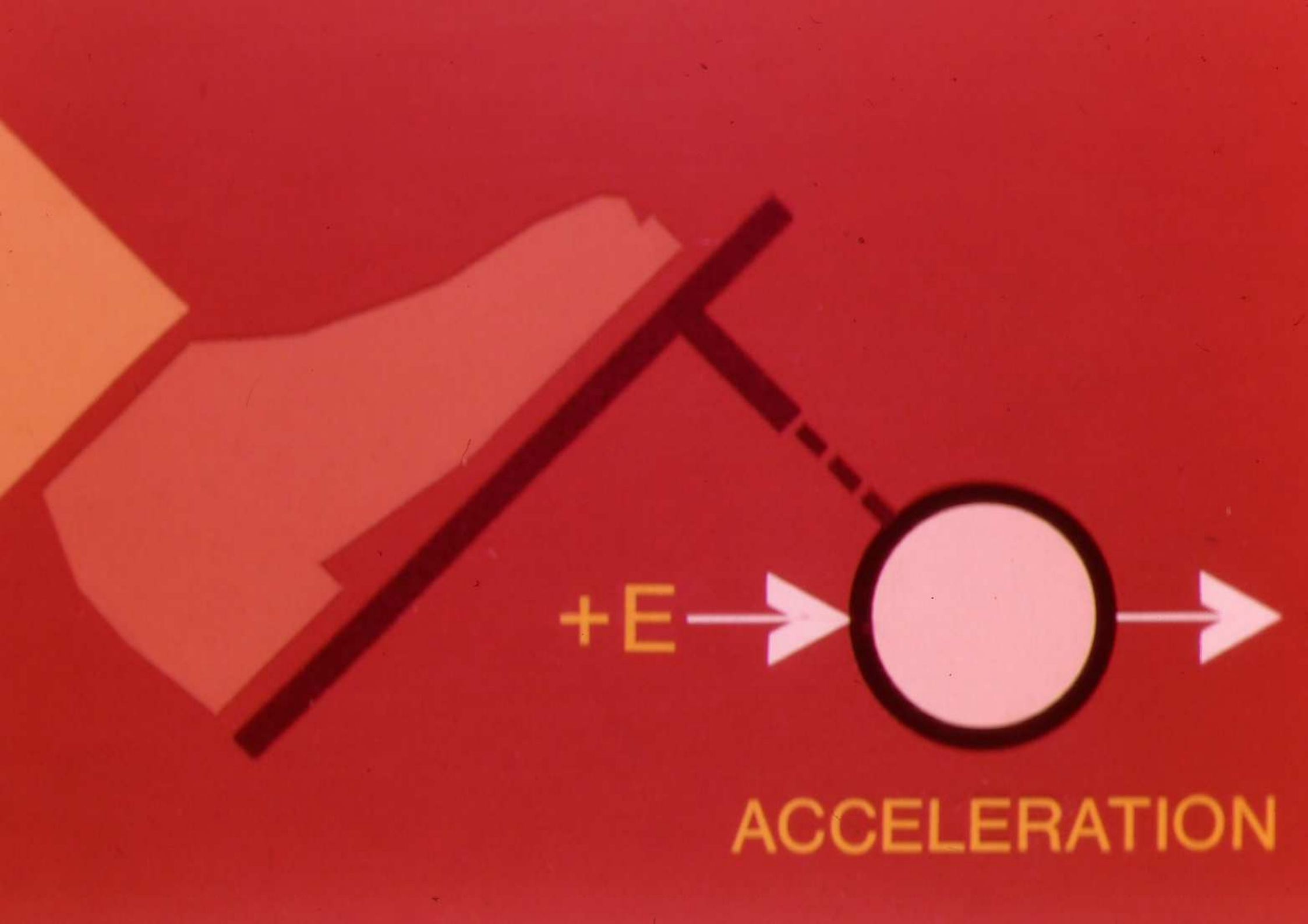


Acceleration

Speed

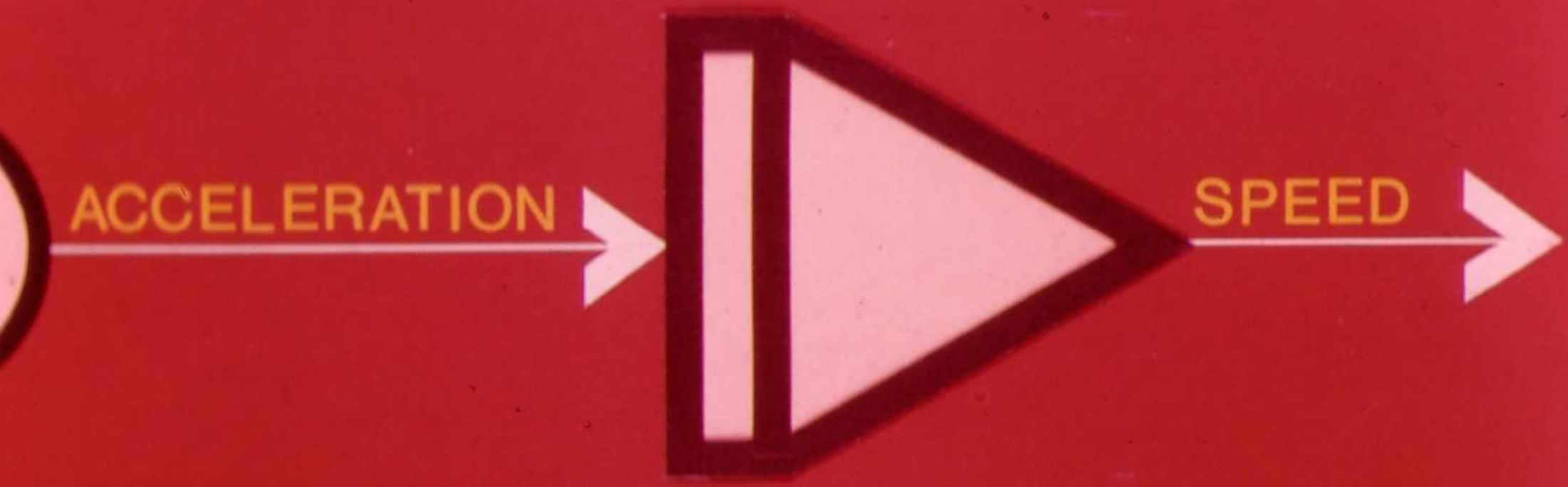
Distance

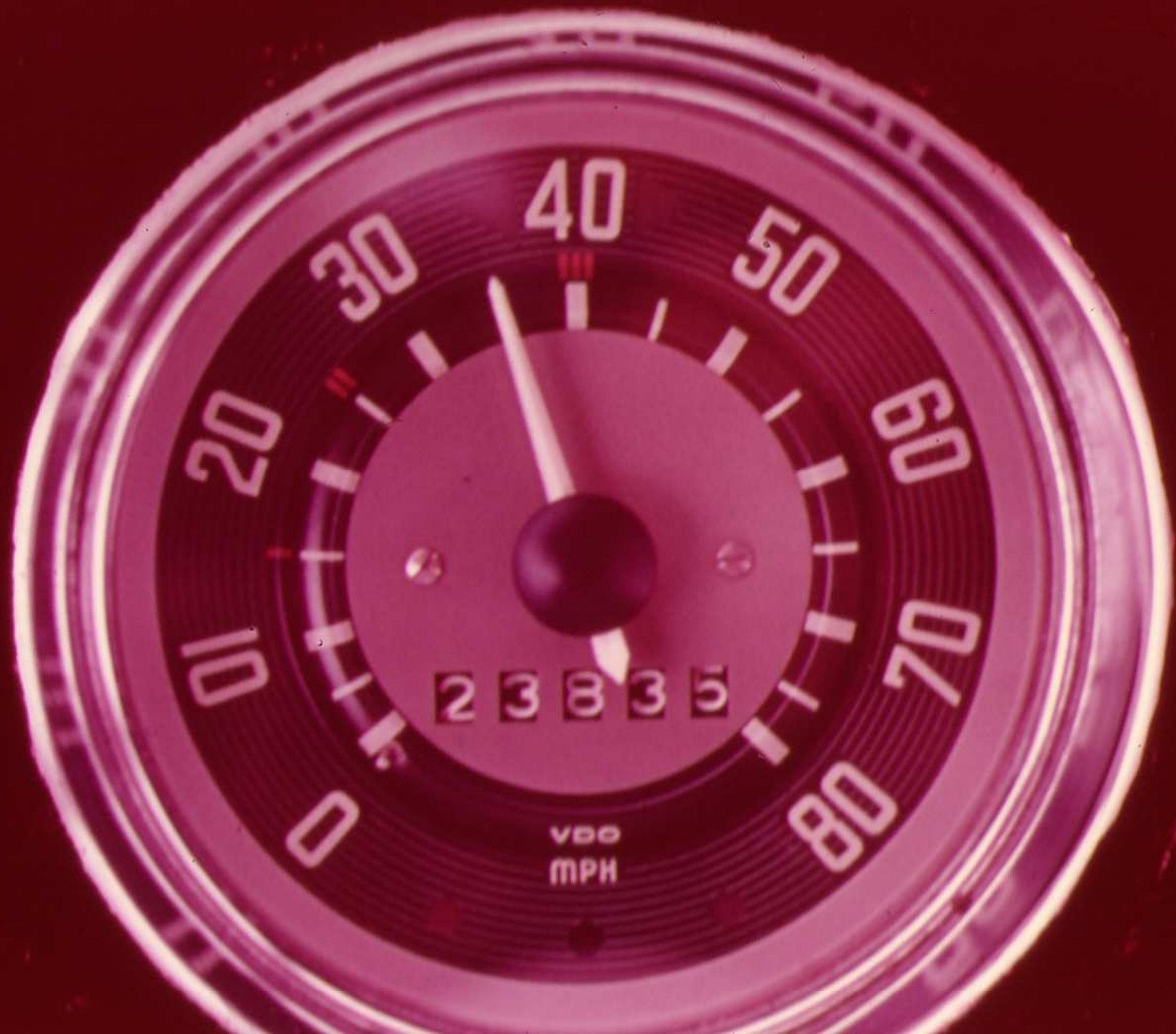




$+E$

ACCELERATION





40

50

30

20

60

70

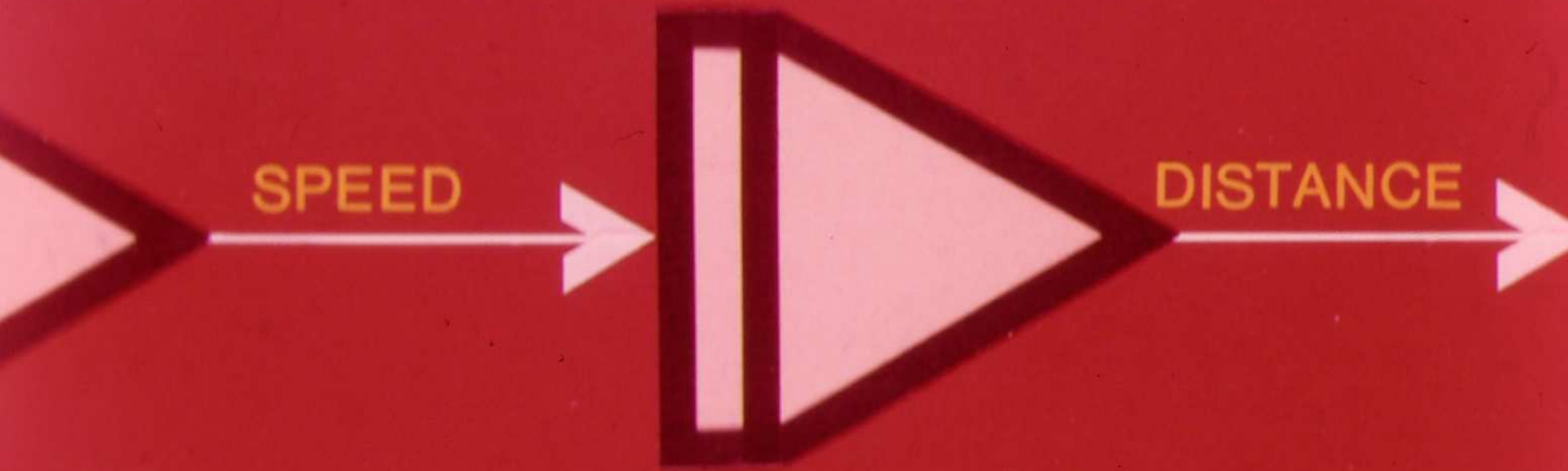
10

0

80

2 3 8 3 5

VDO
MPH





Acceleration

Speed

Distance

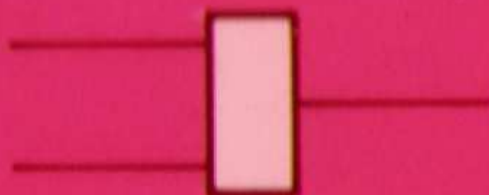


ANALOG/HYBRID

employs digital logic elements to solve non-linear problems



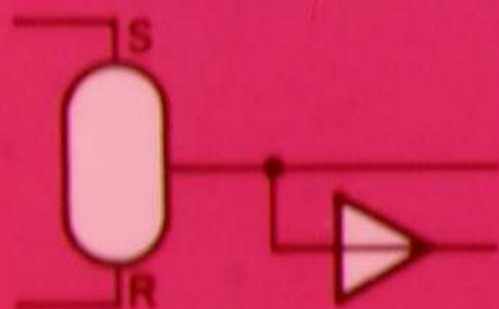
COMPARATOR



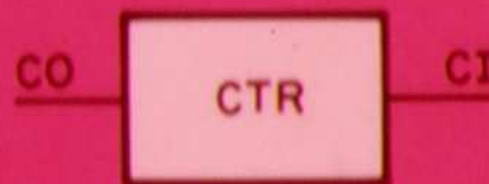
OR GATE



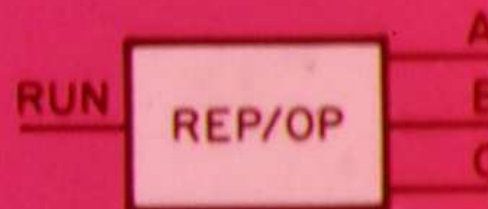
AND GATE



FLIP-FLOP



COUNTER



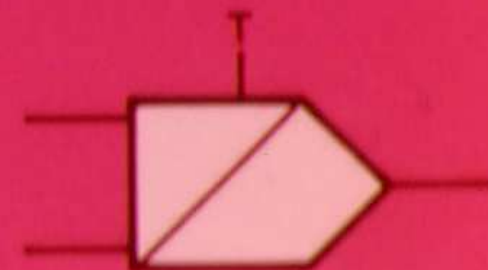
TIMER



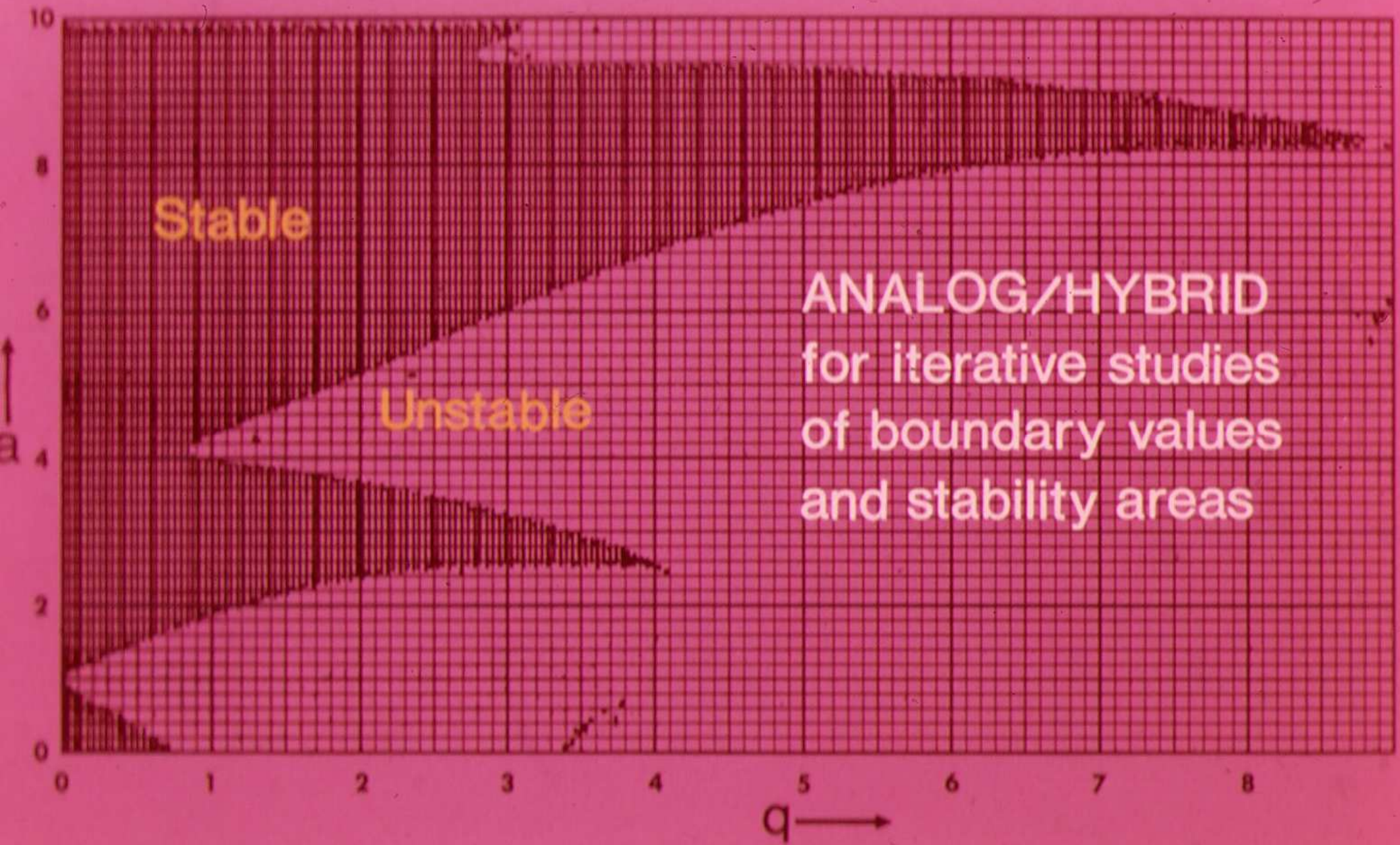
MONOSTABLE



SWITCH

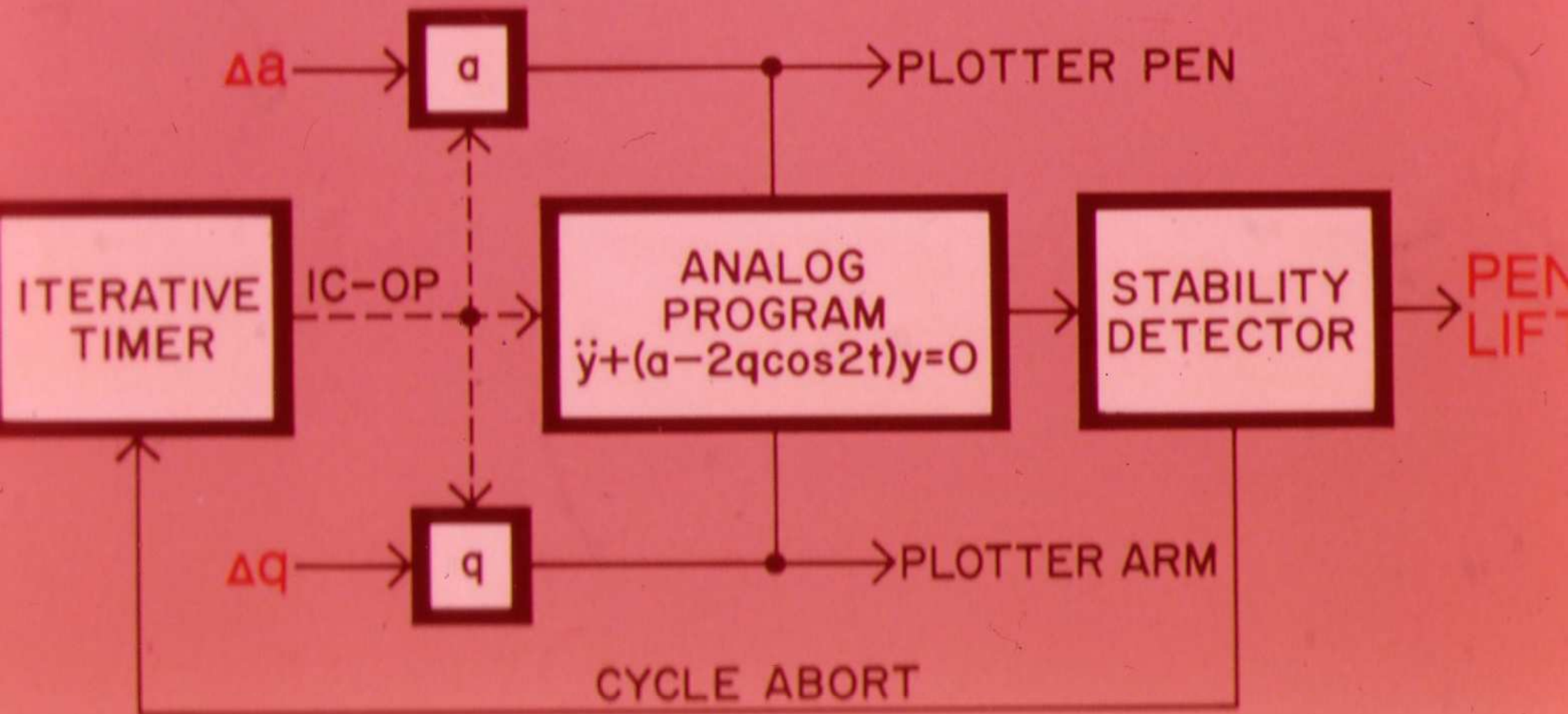


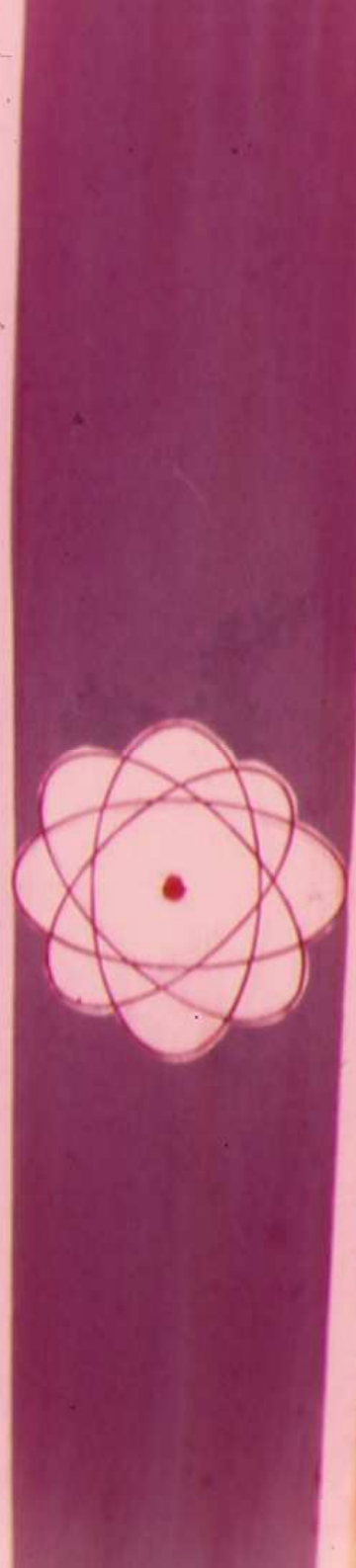
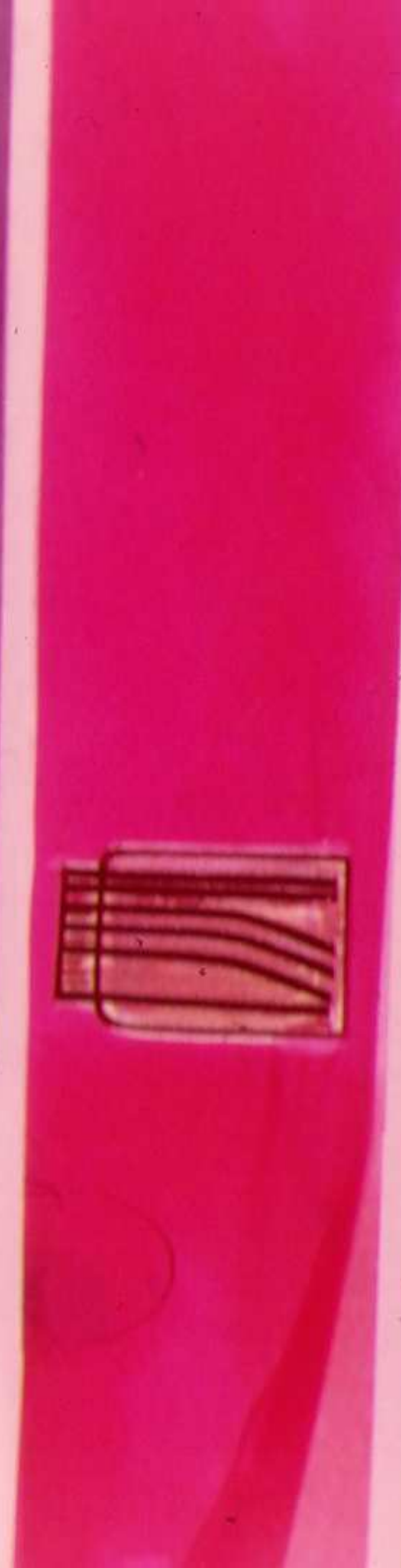
TRACK/STOR

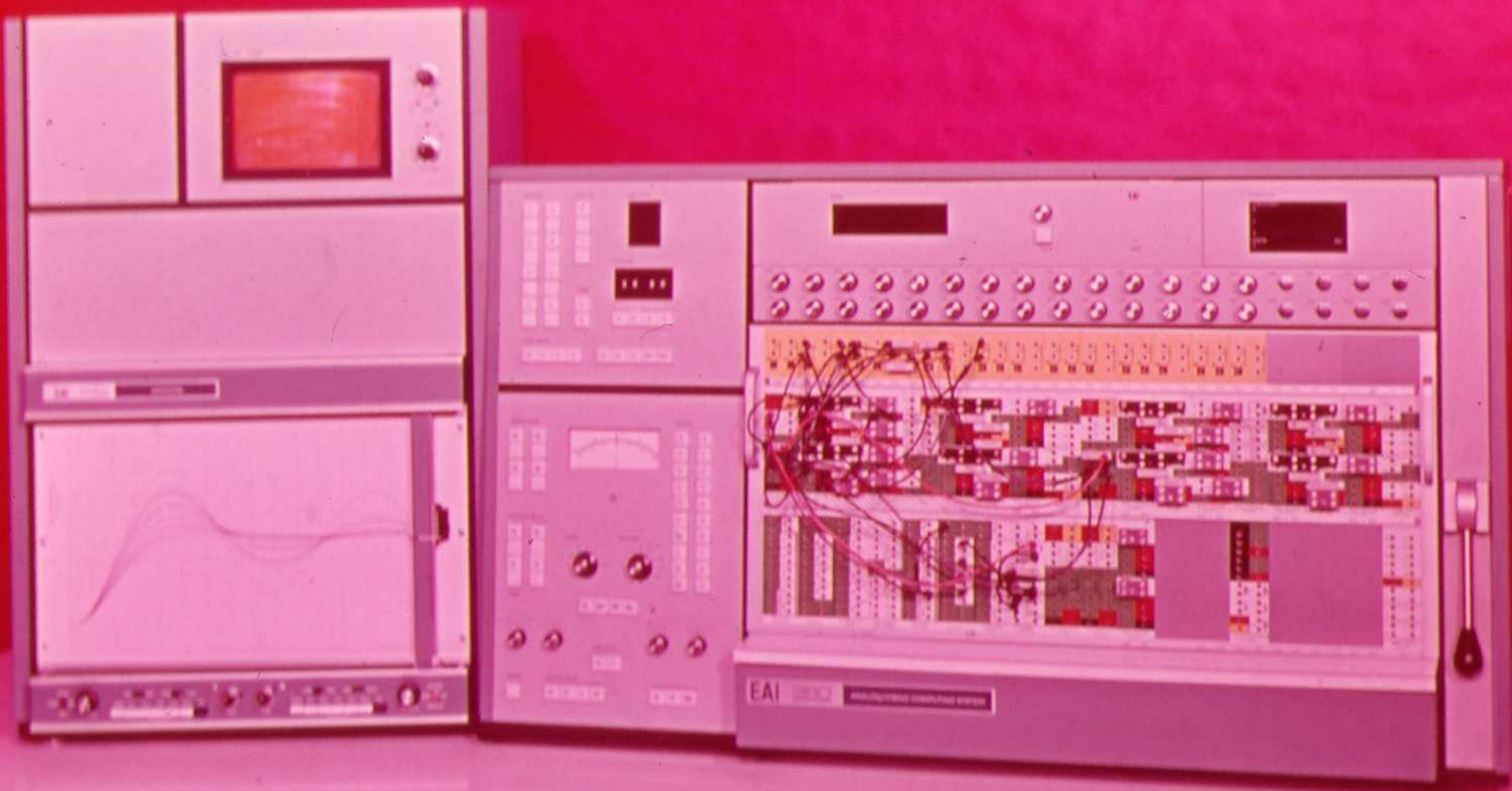


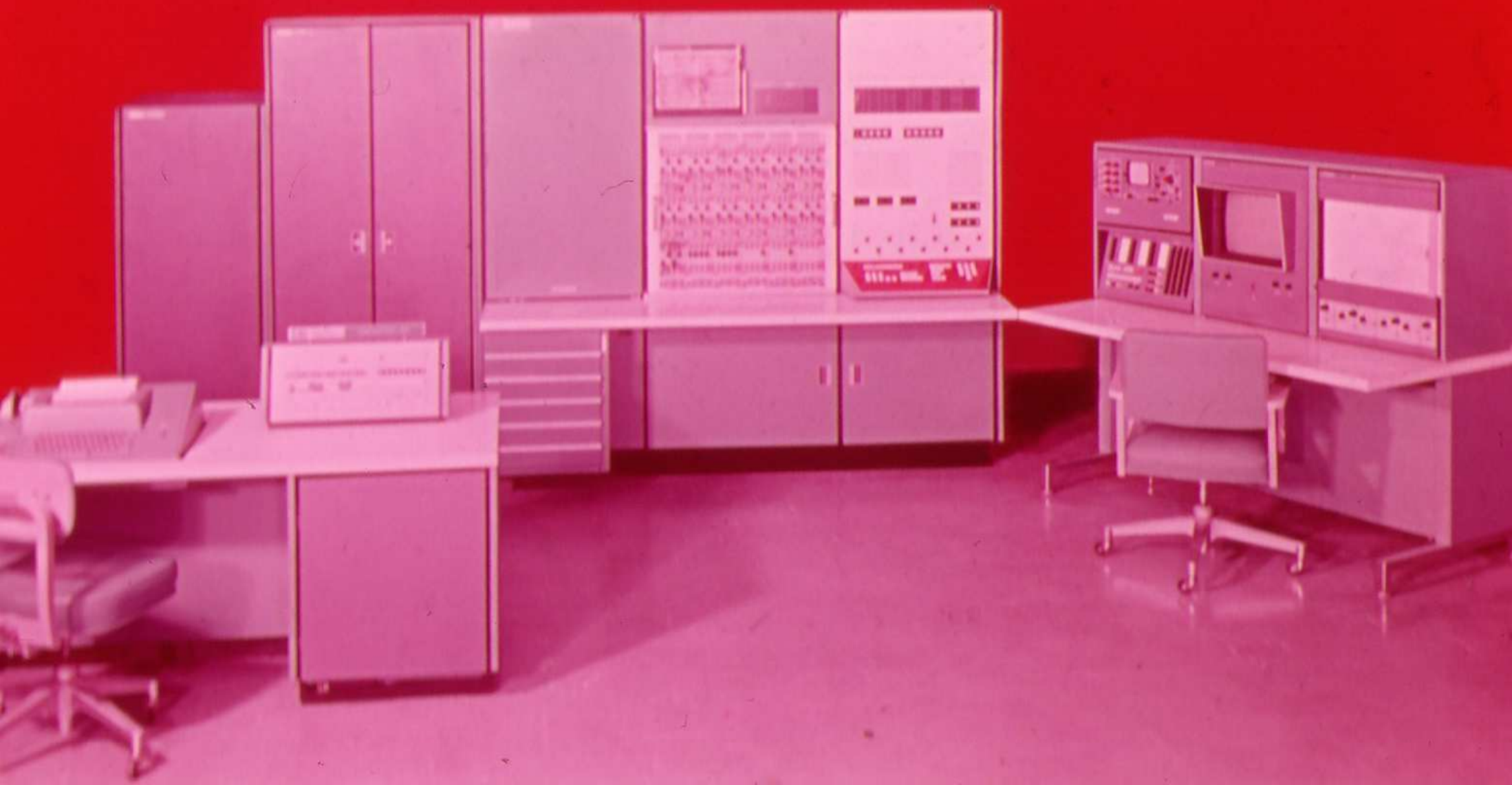
Stability plot for Mathieu's Equation $\ddot{y} + (a - 2q \cos 2t)y = 0$

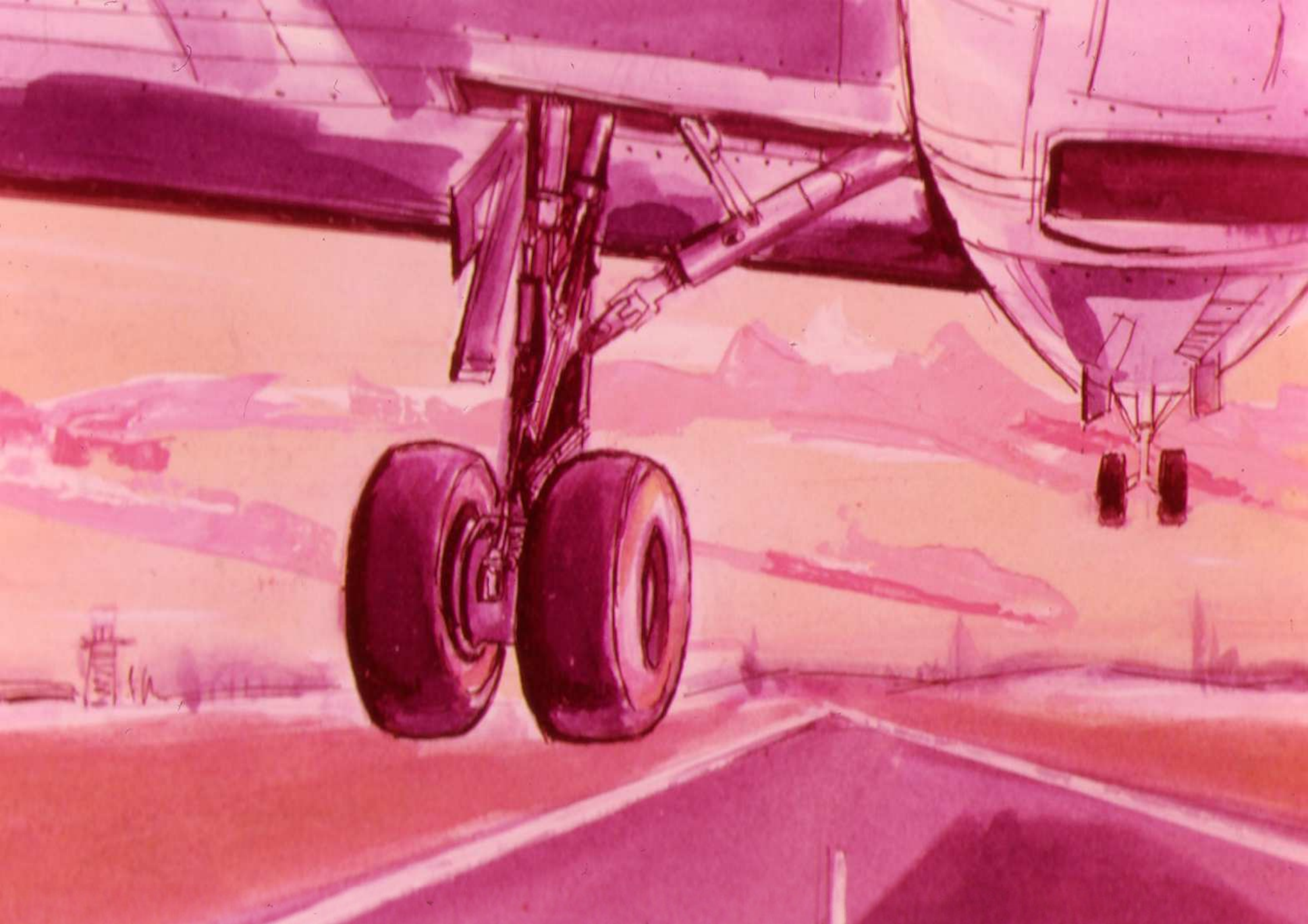
Functional Diagram for program of MATHIEU'S EQUATION







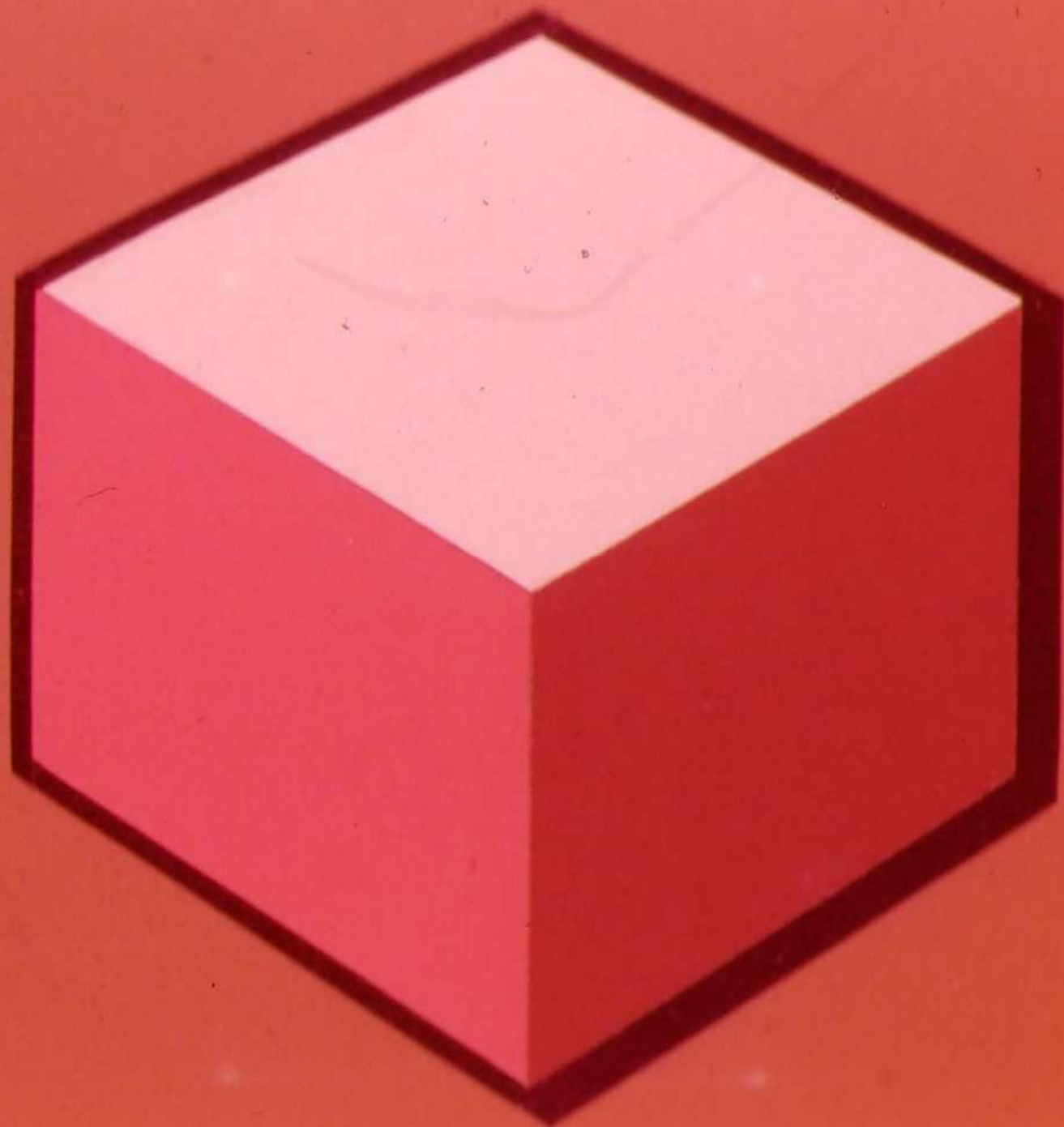




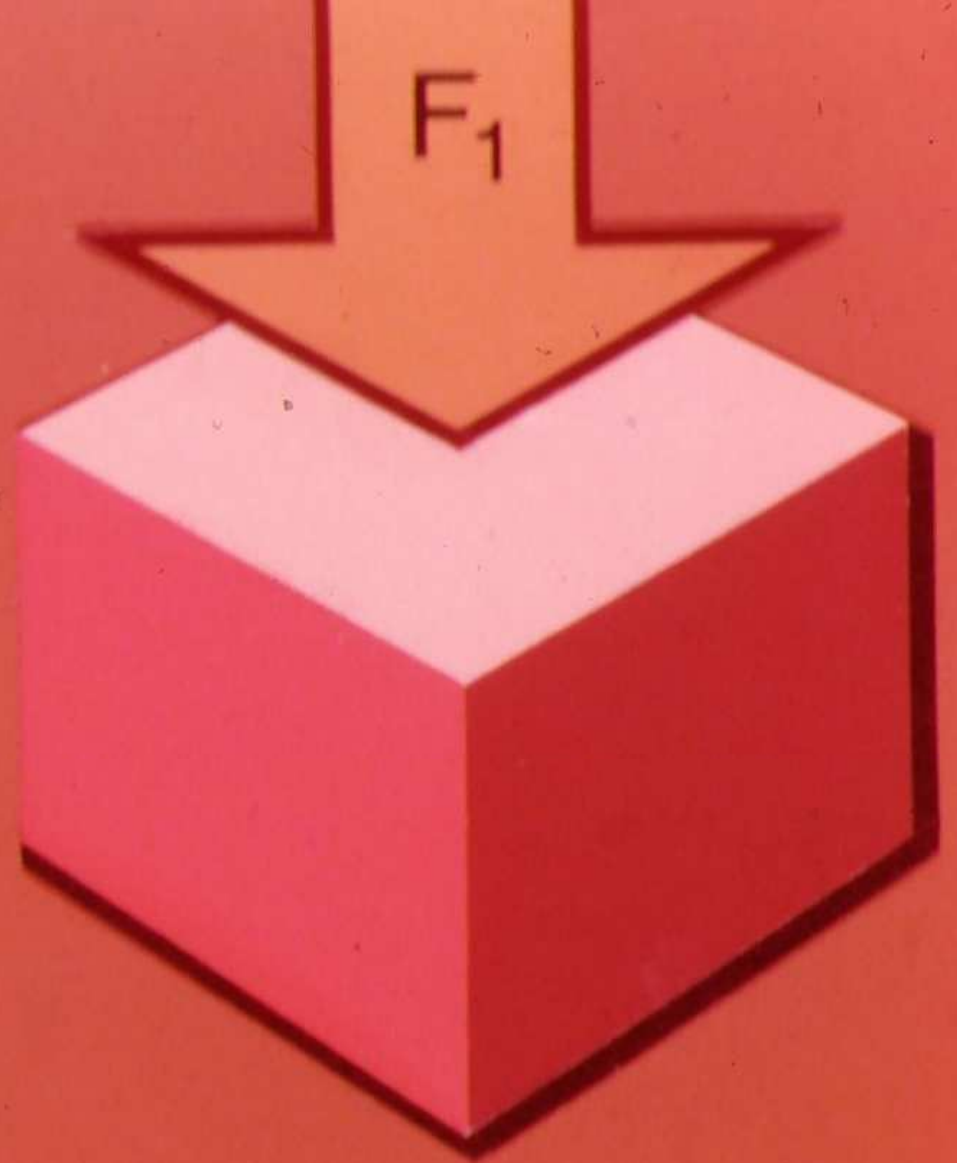
An Example Of Model Building



MASS



$$F_1 = M\ddot{x}$$



FORCE = Mass x Acceleration

SPRING

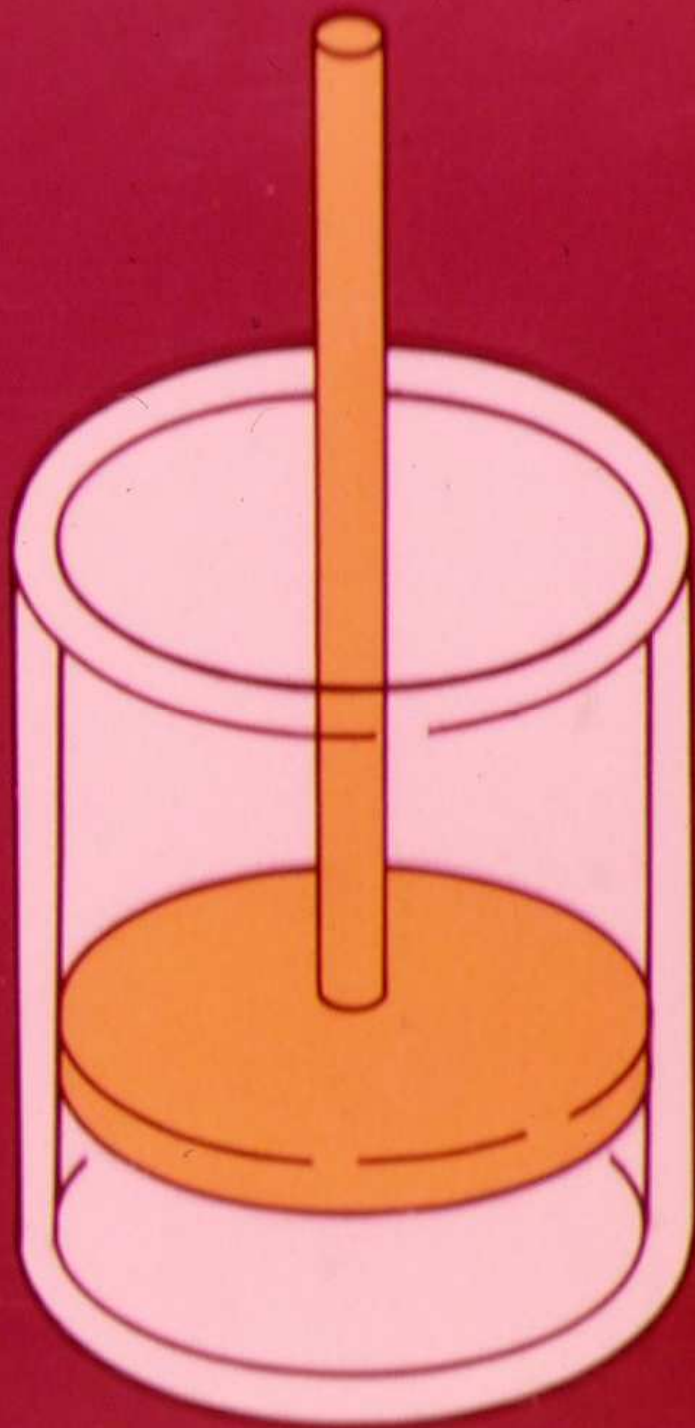


$$F_2 = Sx$$



FORCE=SPRING CONSTANT X DISPLACEMENT

DAMPER

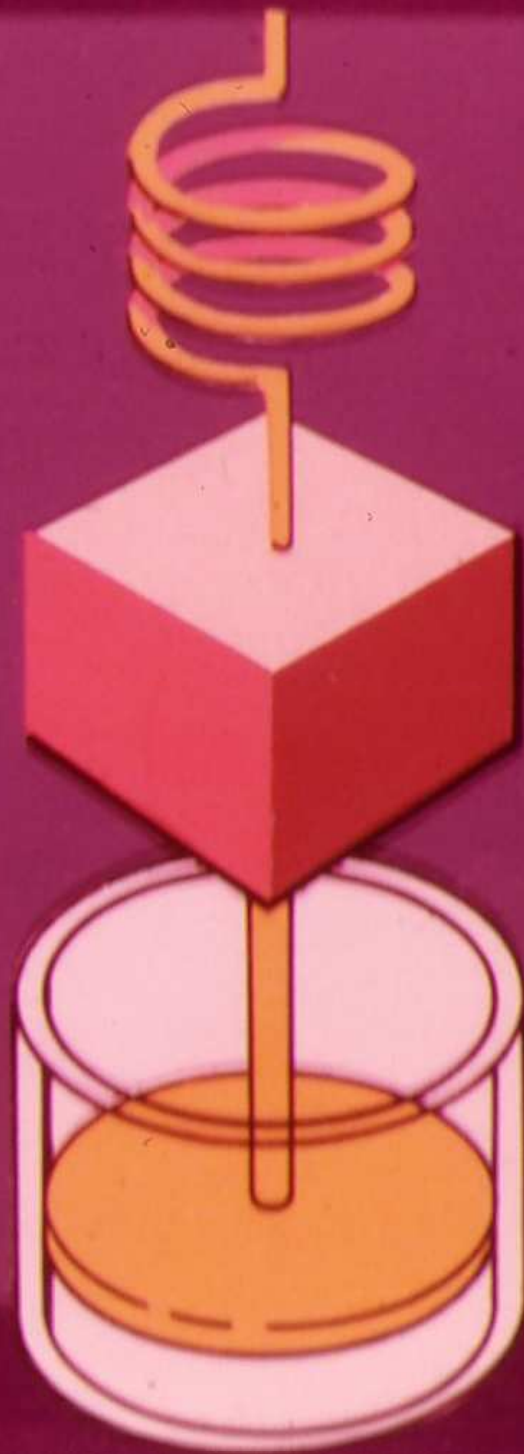


$$F_3 = D\dot{x}$$

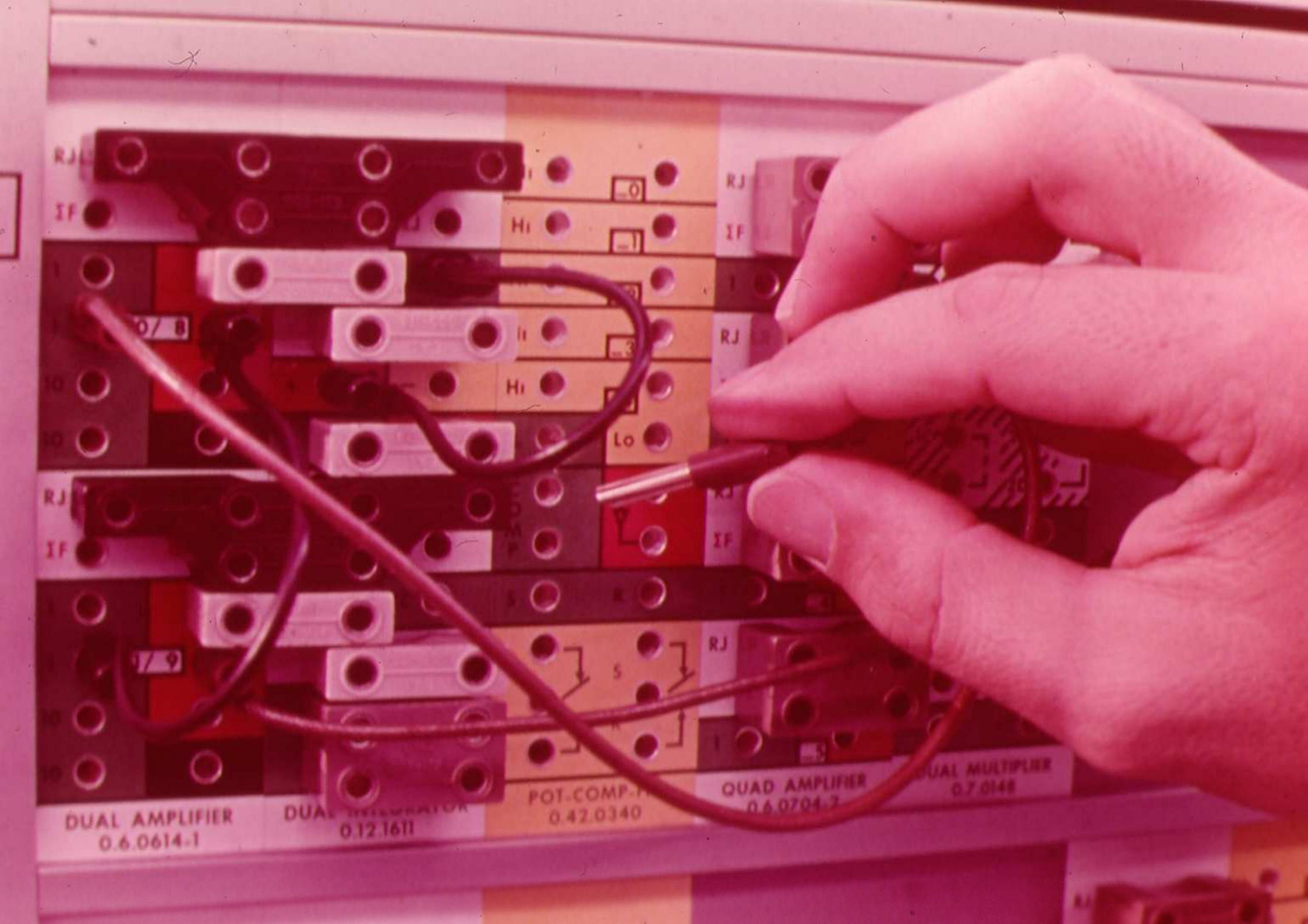


FORCE = Damping Factor x Velocity

$$F_1 + F_2 + F_3 = 0$$



$$M\ddot{x} + D\dot{x} + Sx = 0$$



RJ

IF

RJ

IF

RJ

IF

RJ

RJ

IF

RJ

IF

Hi

Hi

Lo

Ii

Ii

Ii

Lo

Lo

0/8

1/9

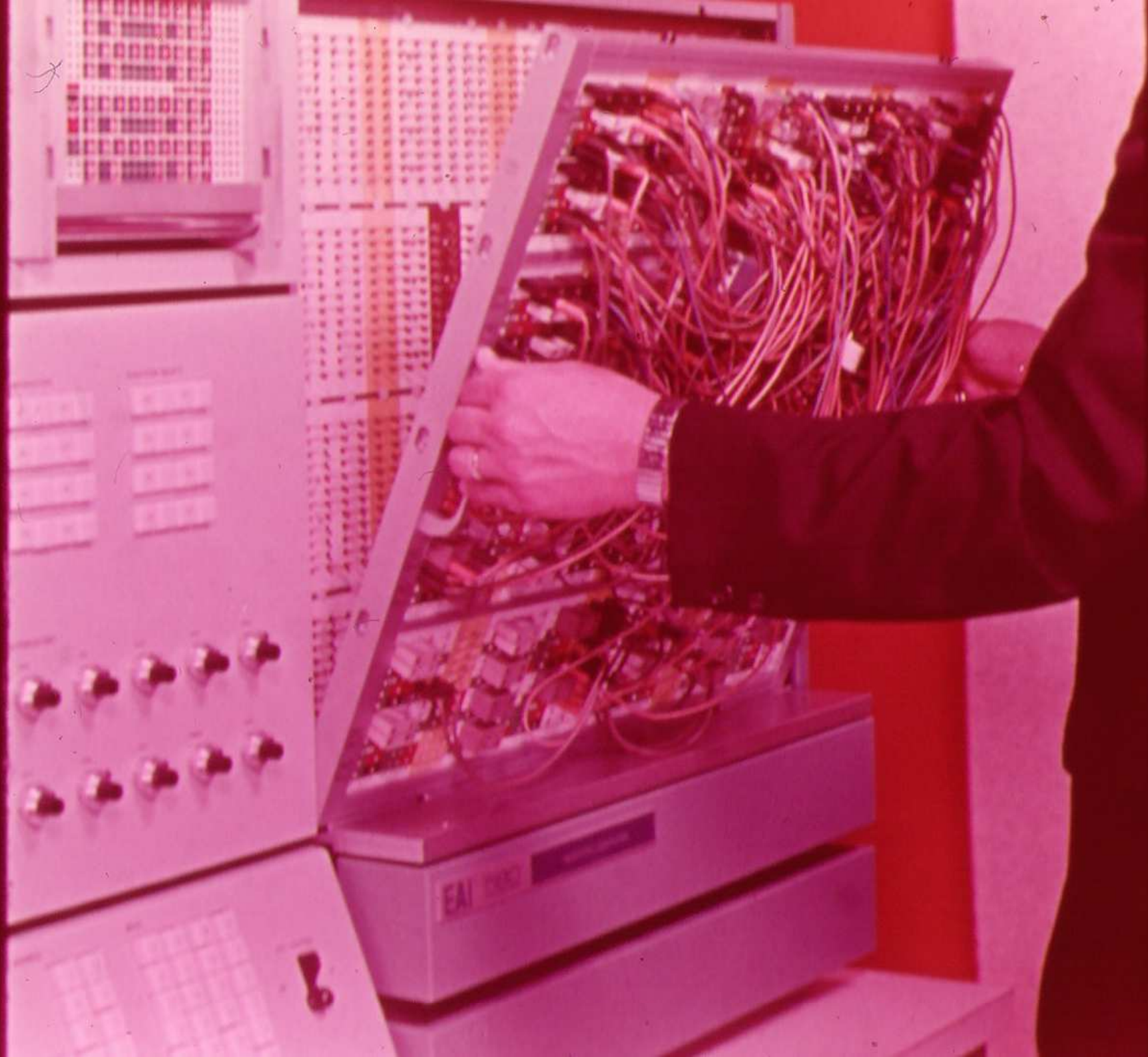
DUAL AMPLIFIER
0.6.0614-1

DUAL MULTIPLIER
0.7.0148

POT-COMP
0.42.0340

QUAD AMPLIFIER
0.6.0704-2

DUAL MULTIPLIER
0.7.0148



ATTENUATORS

P00



P01



P02



P03



P05



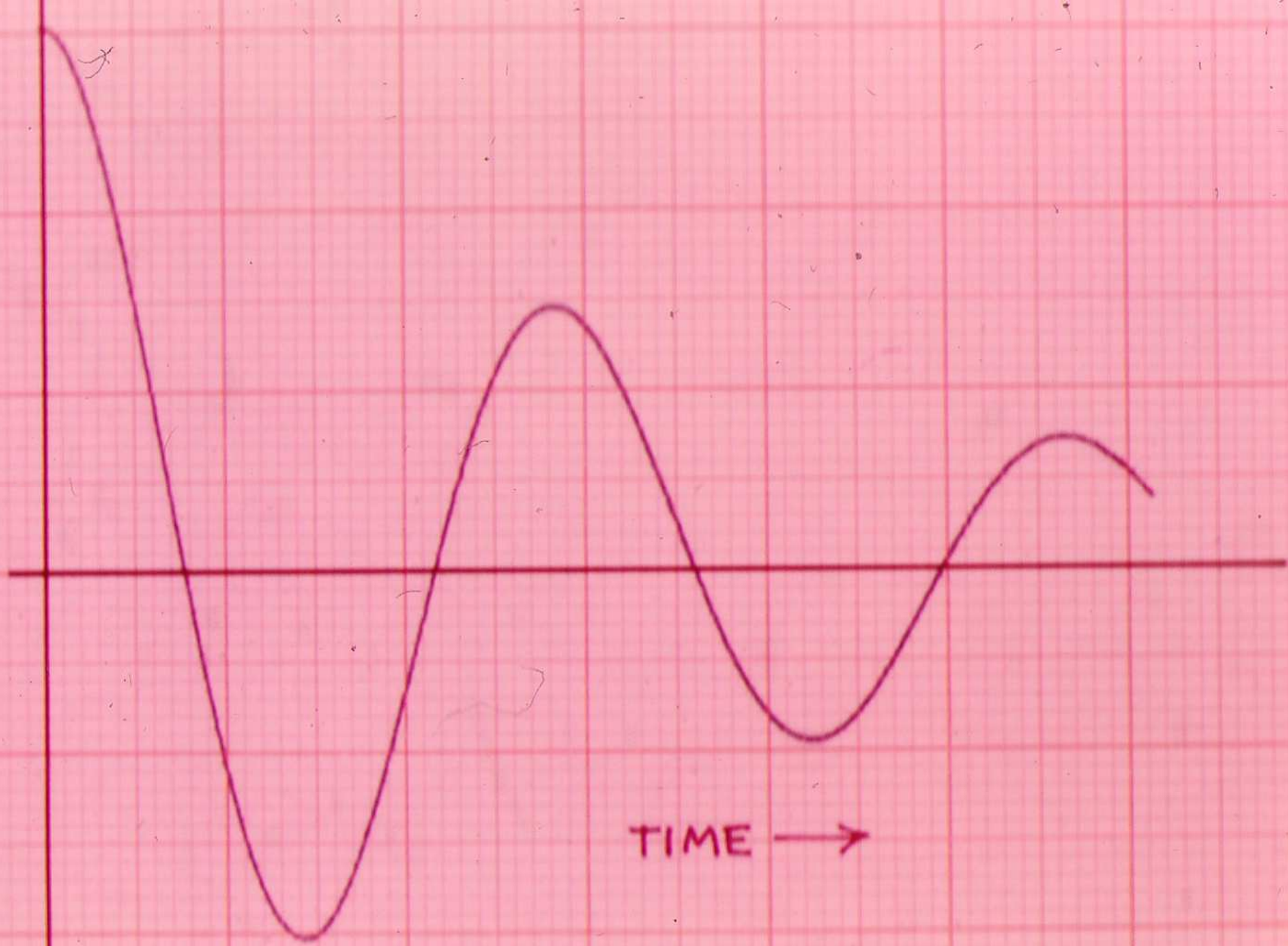
P06



P07



DISPLACEMENT



TIME →



PO4

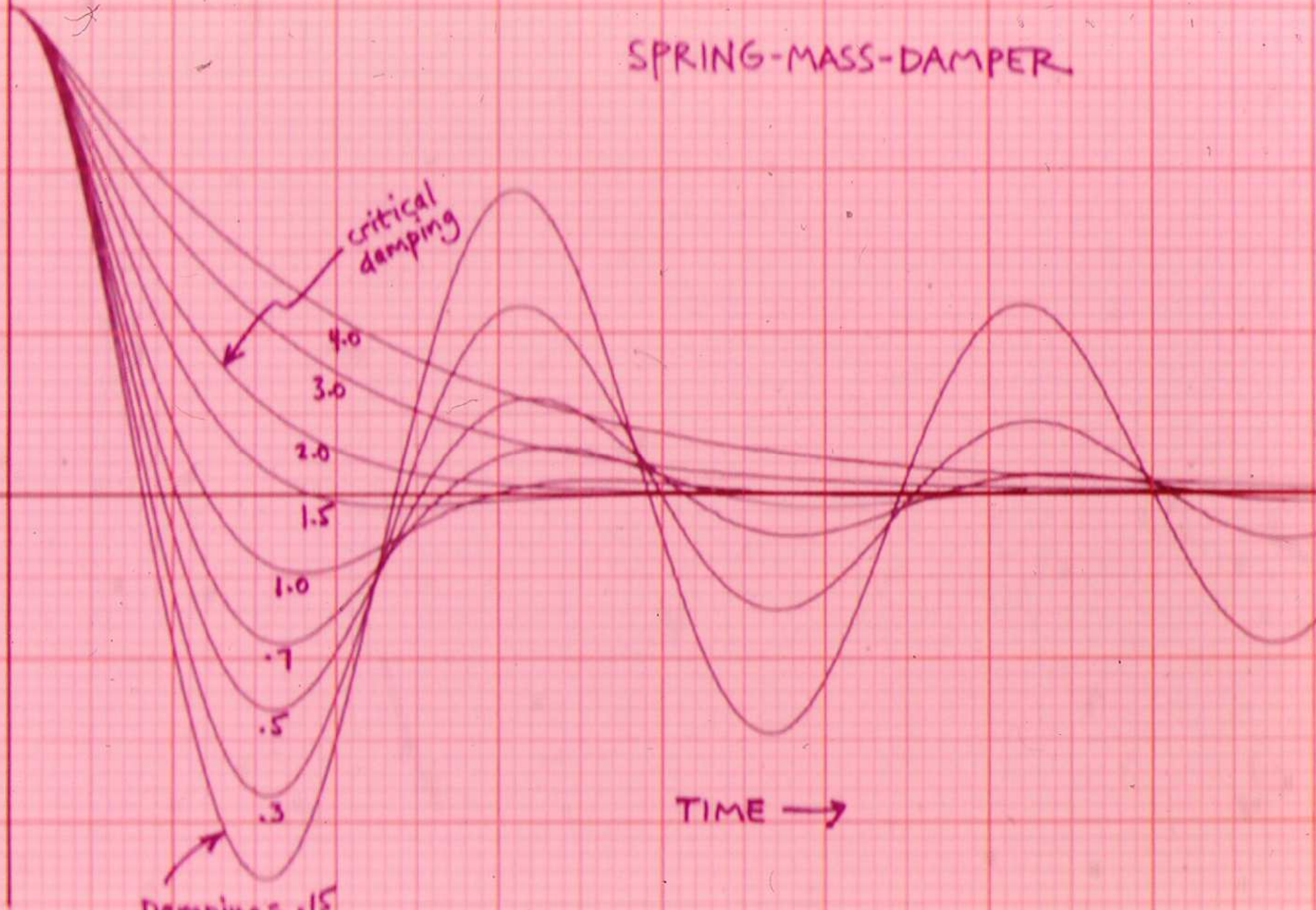


SPRING-MASS-DAMPER

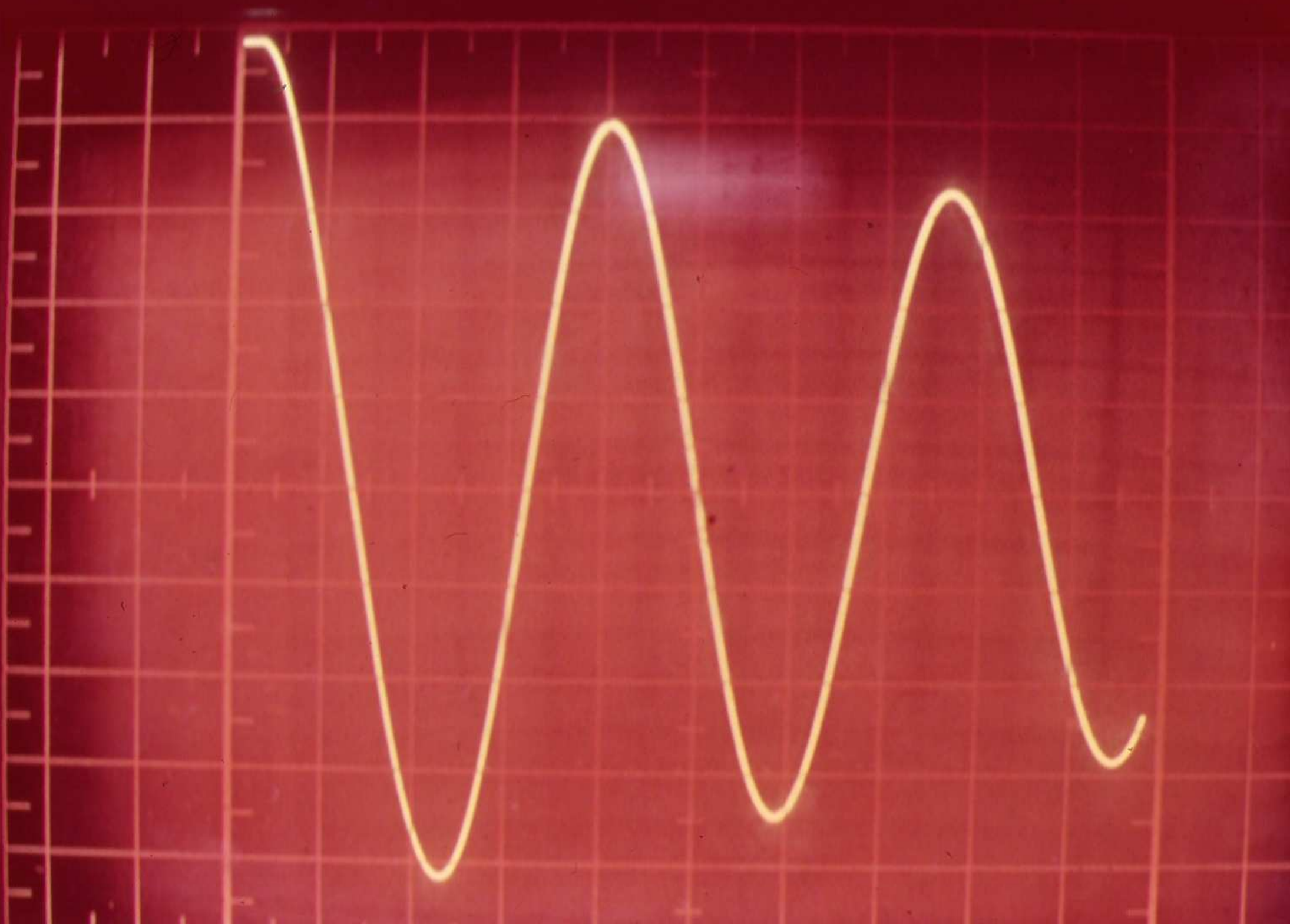
DISPLACEMENT

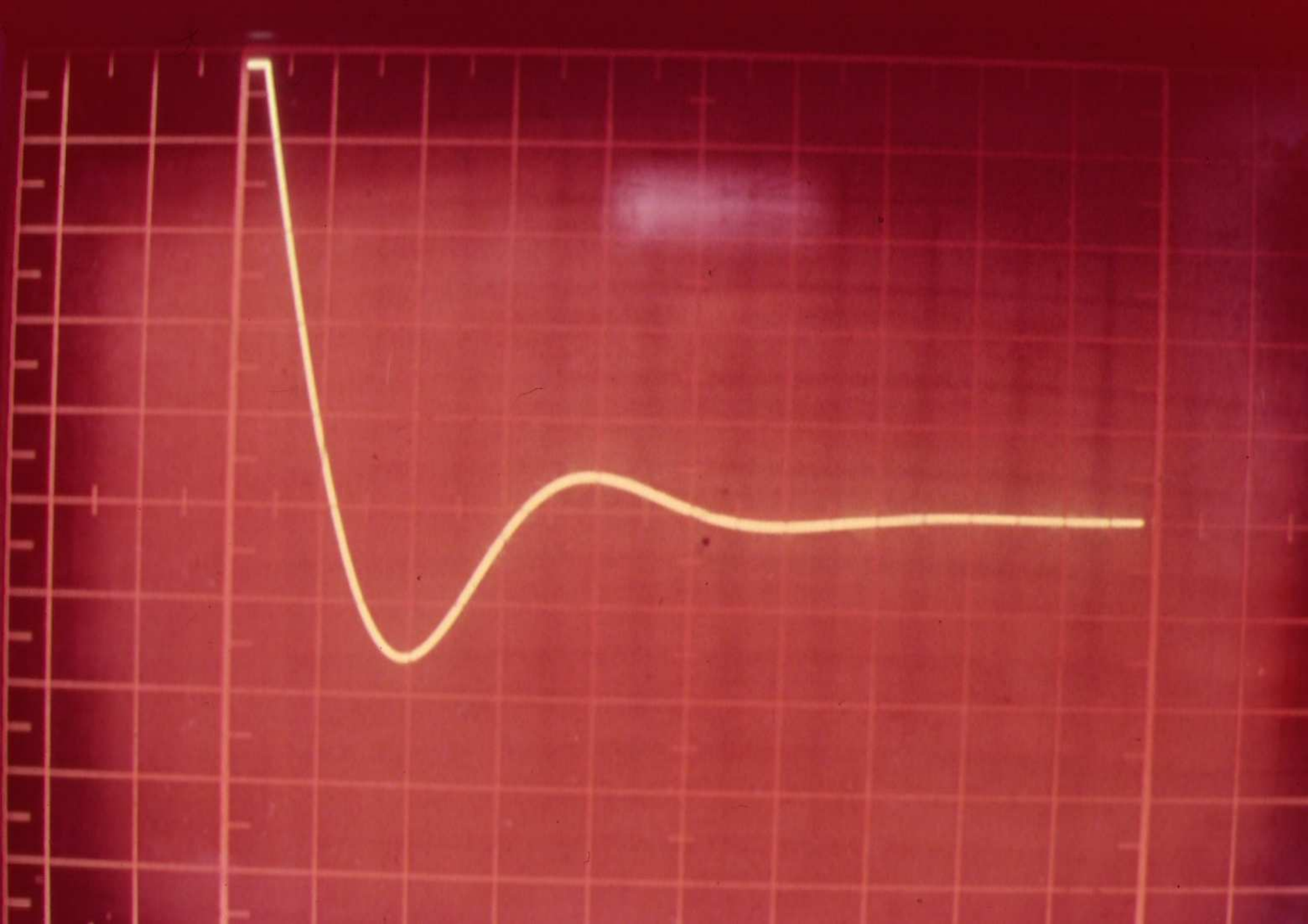
TIME →

critical damping
4.0
3.0
2.0
1.5
1.0
.7
.5
.3
Damping = .15

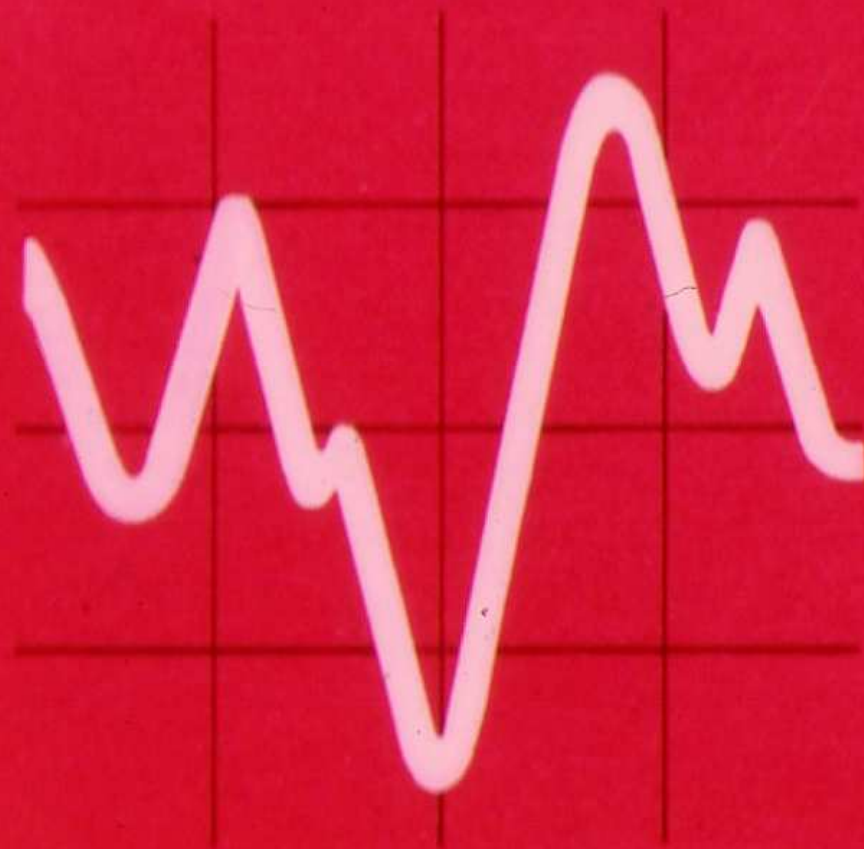












Analog Computer Concepts

ANALOG COMPUTER CHARACTERISTICS

1. VARIABLES are VOLTAGE levels

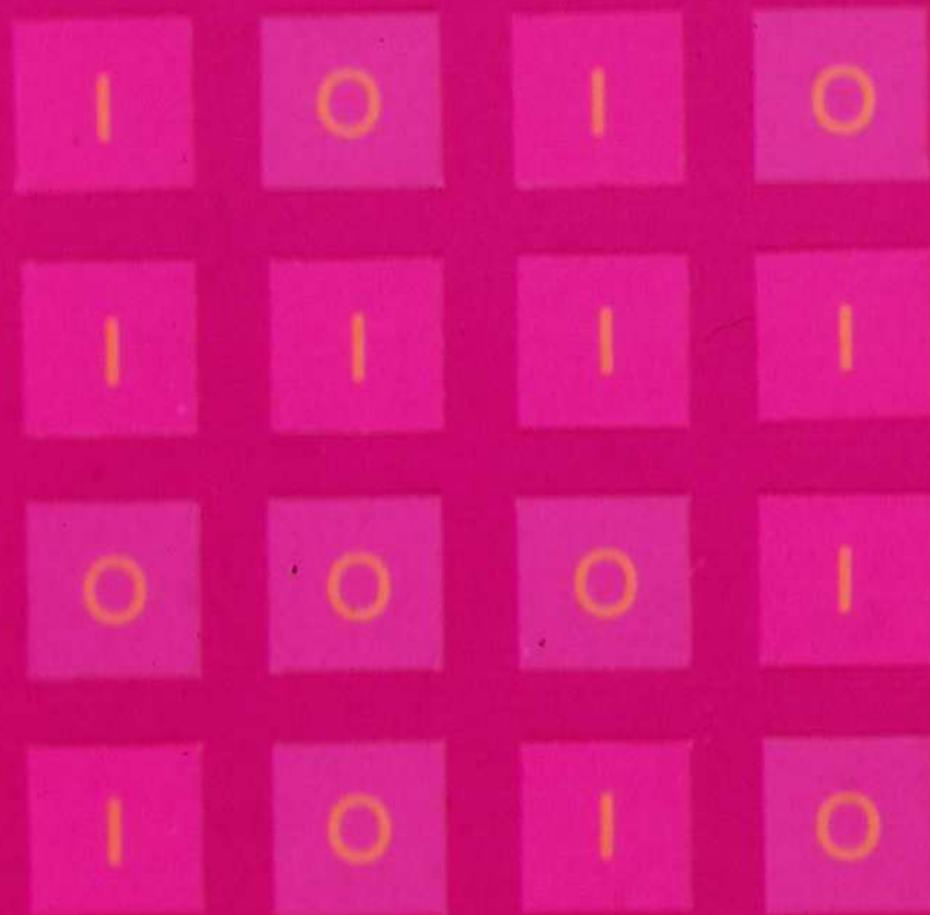
2. OPERATION is CONTINUOUS

3. SIMULATES physical system

4. REAL, FAST, or SLOW TIME

ANALOG/HYBRID employs
DIGITAL LOGIC elements for

DECISION-MAKING
AND CONTROL

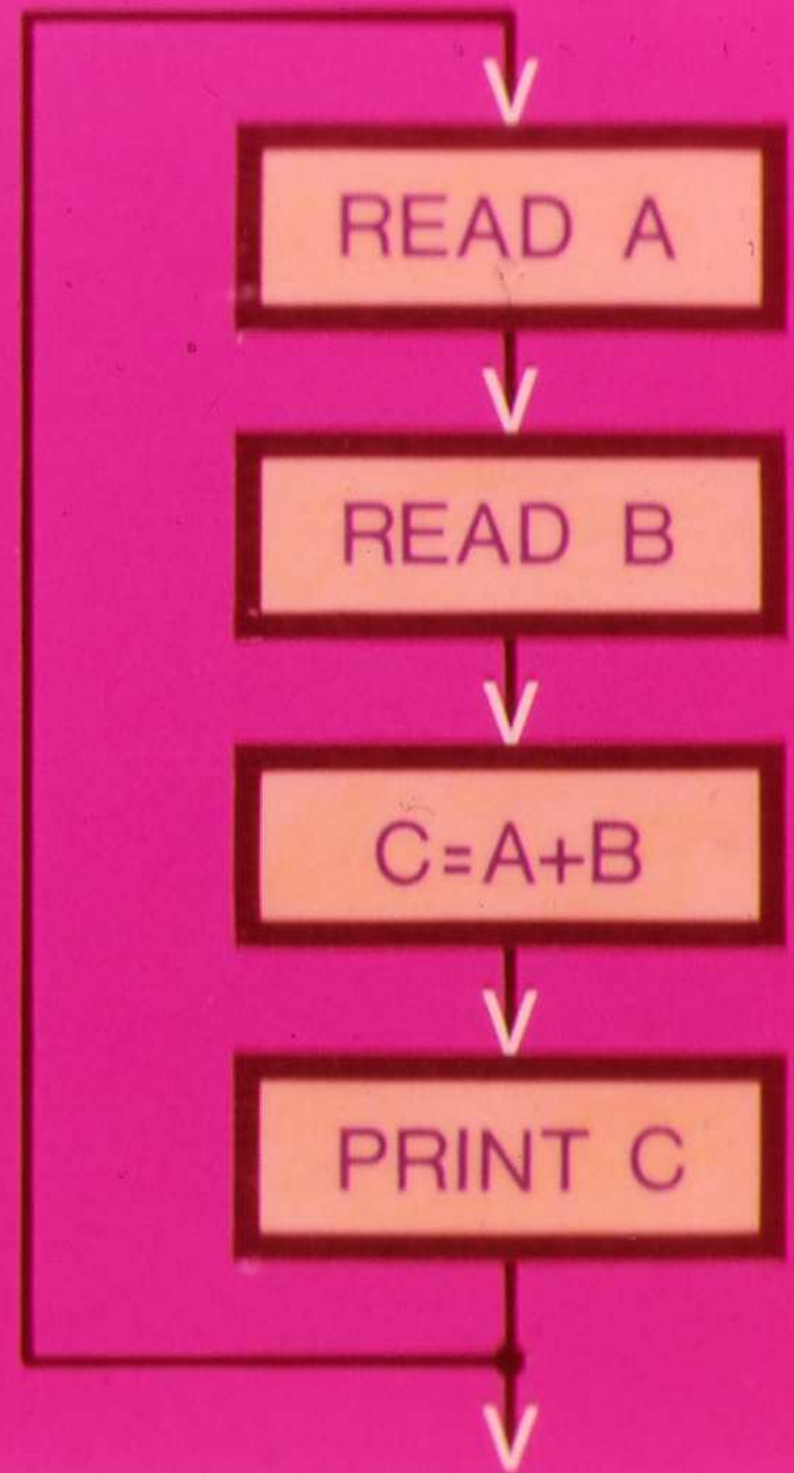


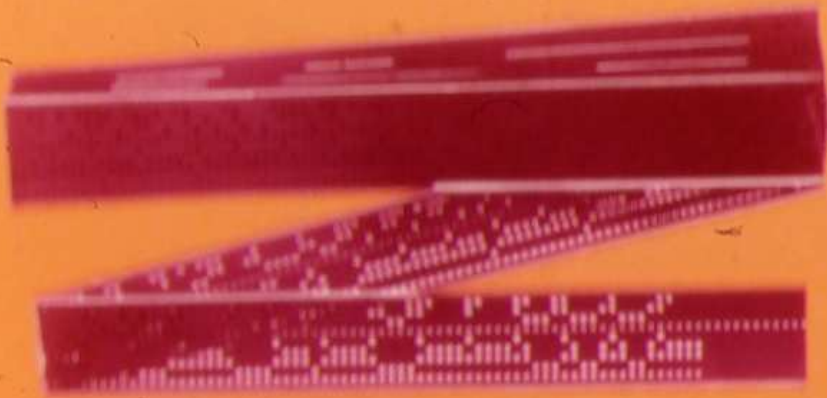
Digital Computer Concepts

DIGITAL uses BINARY number system



DIGITAL operation
is SEQUENTIAL





Punched Tape



Punched Cards



Magnetic Tape



Keyboard

. 12403333

. 13747727+

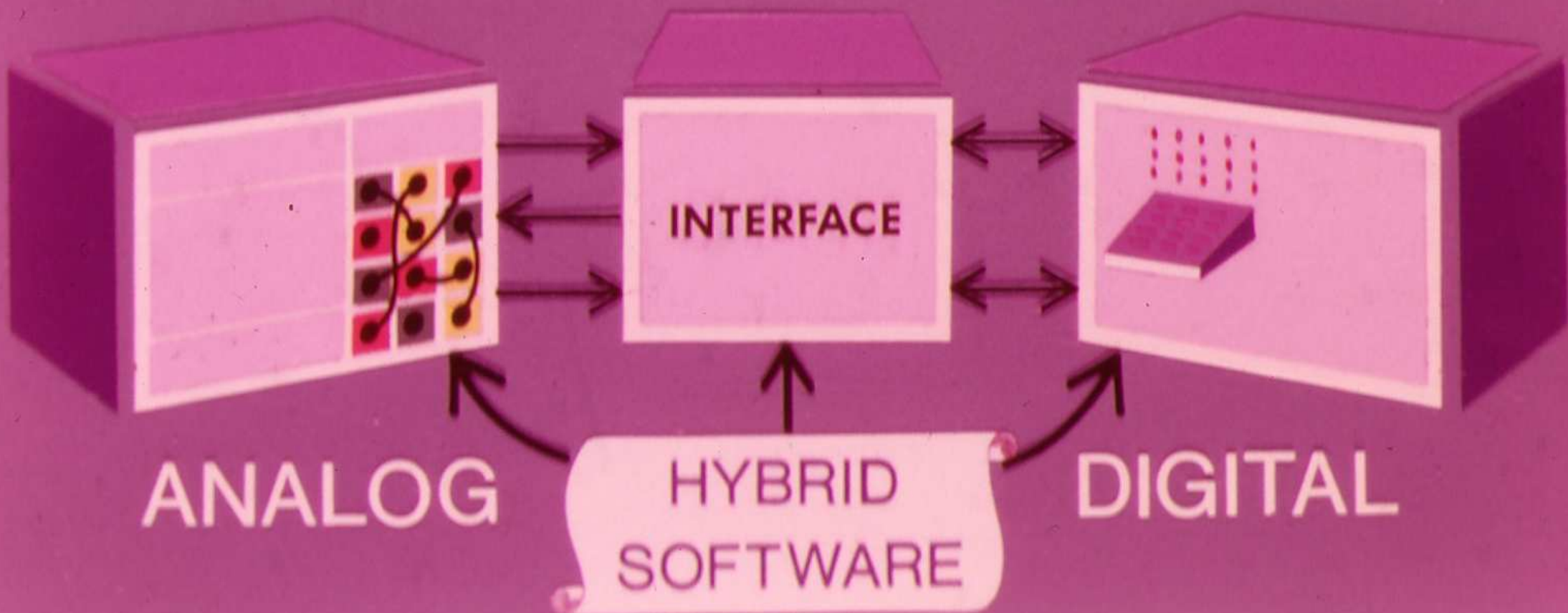
. 14966629+

. 16155494+

. 17320508+

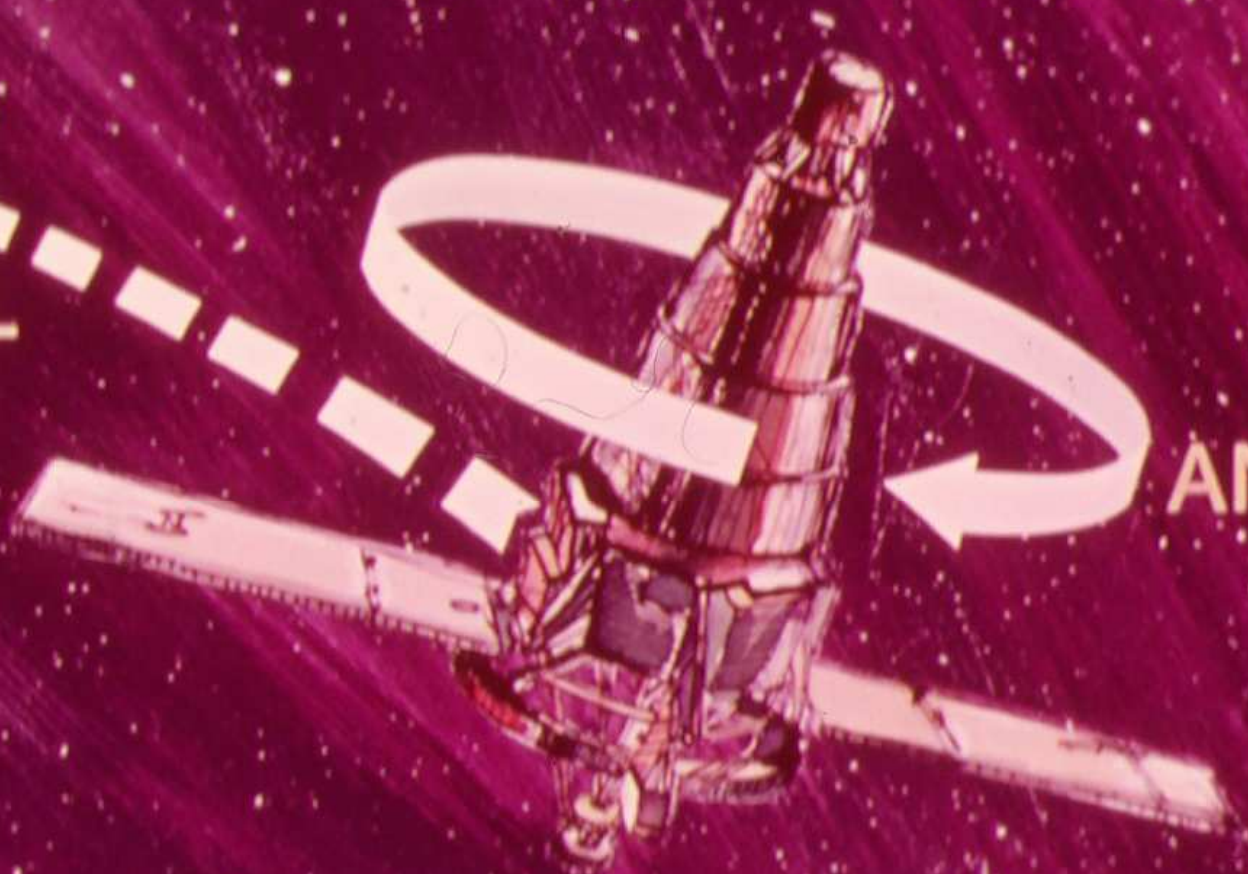
HYBRID SYSTEMS

combine the best features of both
Analog and Digital

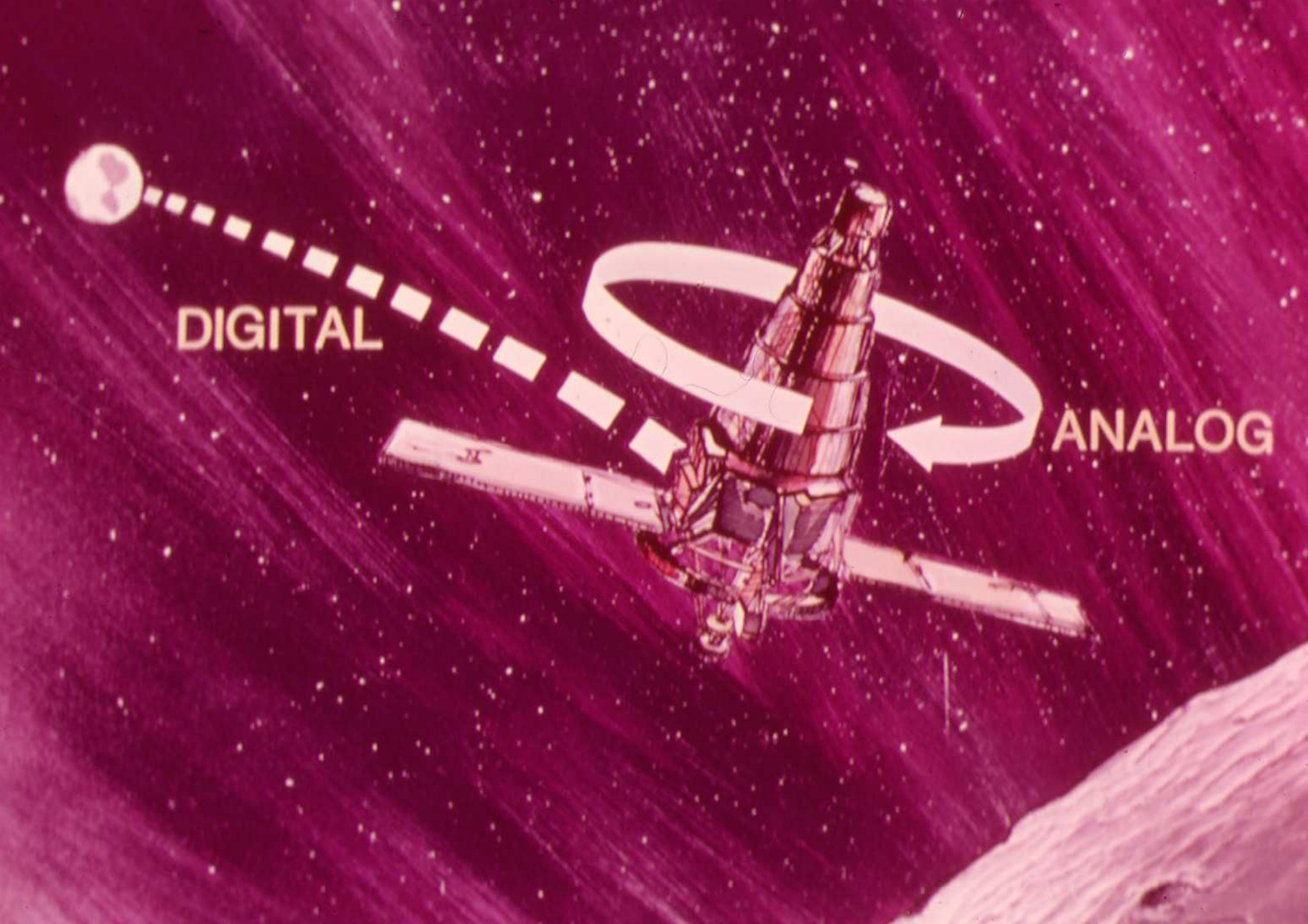




DIGITAL



ANALOG



Analog solves by **SIMULATION**

Operation is **CONTINUOUS**

Components operate in **PARALLEL**

Time **INDEPENDENT** of problem complexity

Analog/Hybrid employs **LOGIC** elements

Used for solving **DYNAMIC PROBLEMS**



THE END